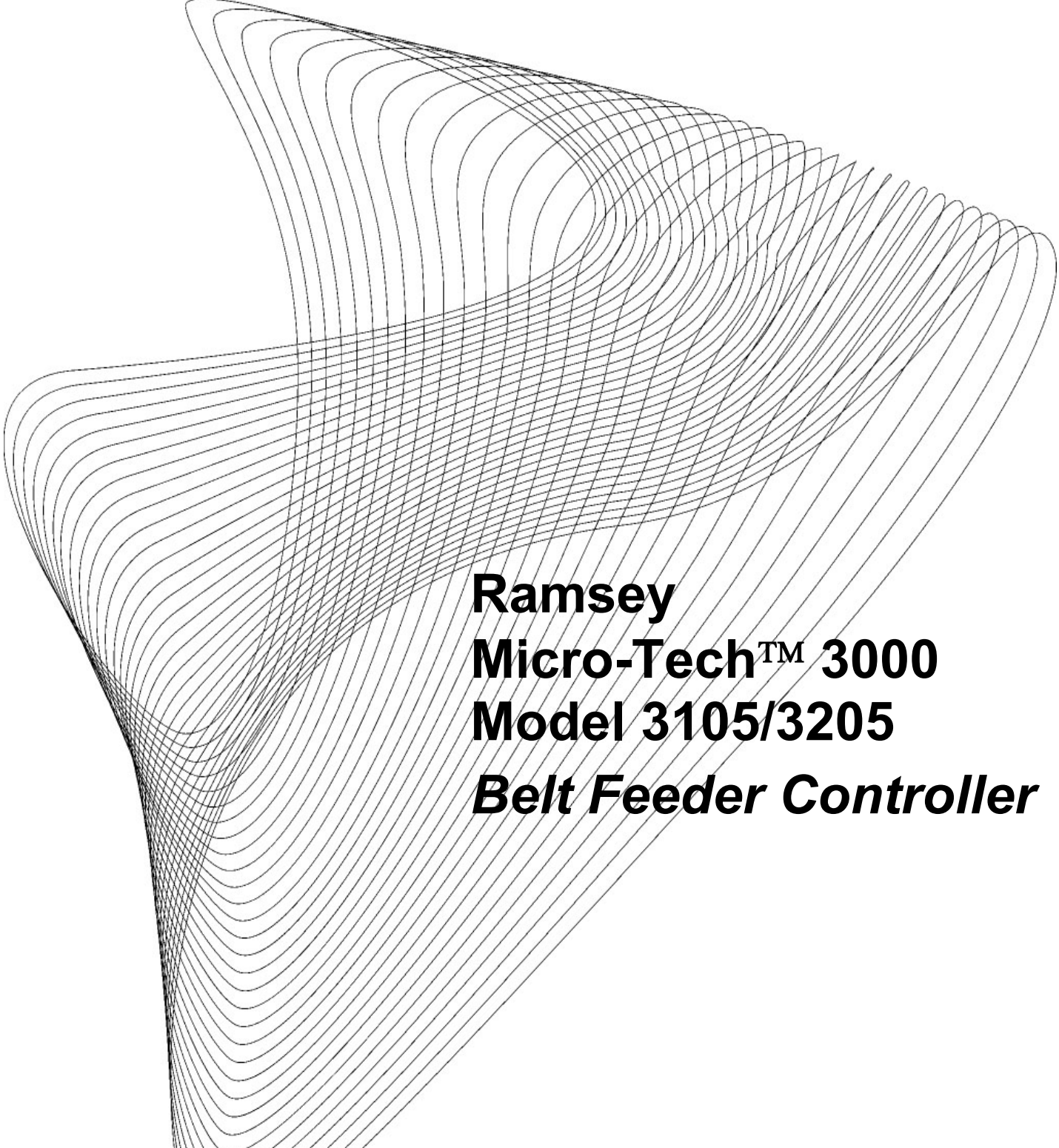


Serial Communications Manual



Ramsey
Micro-Tech™ 3000
Model 3105/3205
Belt Feeder Controller

Serial Comm-
3105/3205 Rev
Part No.: XXXXX

Thermo
ELECTRON CORPORATION

*Ramsey
Micro-Tech™ 3000
Serial Communications
Model 3105/3205
Belt Feeder Controller*

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Chapter 1 Introduction

1.1 General

The Micro-Tech 3105 Belt Feeder Controller is a bus-based microprocessor instrument equipped with one COMM A (on Mother Board) that can be equipped (optionally) with a second serial communication boards. Each COMM A board has one serial channel that can be configured according to the following standards.

- | | |
|----------------|---|
| ! RS423/RS232C | For point to point asynchronous bidirectional communications, maximum 50 feet (15 m). Modem capability. |
| ! RS485/RS422 | For point to point or multidrop 4 wire bidirectional communications, maximum 4000 feet (1200 m). |
| ! Current Loop | For high immunity bidirectional asynchronous communications. Passive only. |

All of the above are optically isolated.

COMM A board (Optionally) can be installed in any available mother board expansion slot. After installing the board and power has been restored, the instrument automatically detects the new board and adds the communication set-up scrolls to the Main Menu scrolls. The Micro-Tech refers to the COMM A on the Mother Board as COM 1, and the COMM A board (if installed) as COM 2.

If two COMM A are available; one can be set up for printing, the other one for transferring data to and from other intelligent devices such as computers and PLC's. The system cannot support two printers or two COMM lines.

Each COMM A contains a perpetual clock/calendar circuit with battery backup. The battery is located on the mother board and is the same battery used for system memory backup. The system automatically detects and uses the clock calendar circuit of the first board and ignores the second.

Time and date set-up screens become visible after the COMM board is installed.

The Micro-Tech 3000 Integrator COMM meets the year 2000 requirements.

1.2 Communication Protocols

When a COMM line is set up for communication (not for a printer), the system is able to send and receive data to and from another device connected to the COMM line. The COMM option comes with the following software communication protocols already built in:

- | | |
|-----------------|--|
| - PC-Master | A Thermo Ramsey proprietary protocol, multidrop. |
| - Modbus | An AEG proprietary protocol, multidrop. The COMM option only contains a subset of the protocol as specified in this manual. |
| - Allen-Bradley | A proprietary protocol, multidrop. The COMM option only contains a subset of the protocol in the PLC-5 version of it, as specified in this manual. |
| - 3964R | A Siemens proprietary protocol, single point. |

The hardware can be configured (through jumpers on the Mother Board and on the optionally COMM board if available) to one of the three standards as listed in the previous paragraph. However, only the RS485/RS422 standard allows multidrop communications, RS232C and Current Loop can only be used in point to point mode. This does not prevent the use of a protocol; it only prevents physically connecting the Micro-Tech 3000 to more than one device.

CAUTION

The communication protocols have been implemented and tested as described in this document or in other referenced documents. It is the intention of Thermo Ramsey to provide all the necessary information and help the user to connect the instrument to other compatible devices. However, because most of the protocols are specific to other manufacturers, Thermo Ramsey declines any responsibility for any malfunction that may occur when connecting the instrument to devices of other manufacturers, unless tested and approved by Thermo Ramsey.

1.2.1 Protocol Rules

The communication protocol allows a remote intelligent device to read and eventually write information from and to the Micro-Tech 3105. For convenience, the information is organized in a set of registers as listed in this document.

During the communication activity, the Micro-Tech 3105 always acts as Slave, meaning it responds to a request from a Master device on the line, but never attempts to send messages out.

The following rules apply:

- a. The Micro-Tech 3105 responds only if the message is completely received.
- b. The Micro-Tech 3105 reads the message and looks for the address, which is contained into an address byte in the query package. The message is then processed only if the address matches the one specified in the set-up data of the Micro-Tech 3105, otherwise it is ignored.
- c. When the system receives a message, the integrity of the message is checked. An answer-back message is prepared if the message is formally correct.
- d. When a message containing a variable to be written in memory is received, the system checks the correctness of the message and, if it is correct, immediately sends the answer-back message. This does not always mean the data is written in memory. The system first checks the register number (which must correspond to a valid address of a variable), then the minimum and maximum limits, and then the password. If data can be accepted, it is stored in memory and the success flag is set to 0 (no error). If not, it is set to 1. To know if the last variables sent have been stored, the Master checks (reads) the success flag contained in a read only register.

The following procedure applies:

- The Host sends data to the Micro-Tech 3105.

- The Host waits at least 100 ms.
- The Host reads the success flag. It should be 0.

Some data is read only, some is read write, and some is write only.

WARNING

In all cases, the maximum number of words the system can transfer is limited to 41 per time. Requests of registers in excess of 41 are considered errors and do not generate an answer.

1.3 Printer

When a COMM line is set up for printing, the system prints out data in different ways, depending on the set-up. Print menus become visible that allow the user to define when and in which format the data is printed.

1. Periodical printouts at predefined intervals, as well as at predefined times of day, or on command is possible.
2. The format of the printouts is selectable between a number of predefined formats, plus a fully programmable user defined format. In this particular case, the user is able to easily format the printout to fit into any pre-printed ticket or form, without the need of special software.

1.4 Thermo Electron Warranty

The seller agrees, represents, and warrants that the equipment delivered hereunder shall be free from defects in material and workmanship. Such warranty shall not apply to accessories, parts, or material purchased by the seller unless they are manufactured pursuant to seller's design, but shall apply to the workmanship incorporated in the installation of such items in the complete equipment. To the extent purchased parts or accessories are covered by the manufacturer's warranty, seller shall extend such warranty to buyer.

Seller's obligation under said warranty is conditioned upon the return of the defective equipment, transportation charges prepaid, to the seller's factory in Minneapolis, Minnesota, and the submission of reasonable proof to seller prior to return of the equipment that the defect is due to a matter embraced within seller's warranty hereunder. Any such defect in material and workmanship shall be presented to seller as soon as such alleged errors or defects are discovered by purchaser and seller is given opportunity to investigate and correct alleged errors or defects and in all cases, buyer must have notified seller thereof within one (1) year after delivery, or one (1) year after installation if the installation was accomplished by the seller.

Said warranty shall not apply if the equipment shall not have been operated and maintained in accordance with seller's written instructions applicable to such equipment, or if such equipment shall have been repaired or altered or modified without seller's approval; provided, however, that the foregoing limitation of warranty insofar as it relates to repairs, alterations, or modifications, shall not be applicable to routine preventive and corrective maintenance which normally occur in the operation of the equipment.

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Purchaser agrees to underwrite the cost of any labor required for replacement; including time, travel, and living expenses of *Thermo Electron Field Service* Engineer at closest factory base.

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Chapter 2 Installation

2.1 General

This chapter describes the installation procedure and hardware configuration for the communications (on Mother Board and on Comm A Board option). If the communication option was installed at the factory, it may not be necessary to continue with this chapter. Proceed to Chapter 3.0, Operation.

2.2 Comm A Board (Option) Installation

To install the COMM A board, proceed as follows:

1. Select the jumper positions on the COMM A board for the desired communication standard. Below is a table which summarizes the jumper positions for selection of the electrical interface. Refer to Figure 2-1 for jumper locations.

**TABLE 2-1
COMM A BOARD JUMPERS**

JUMPERS						
Mode	OP1	OP2	OP3	OP4	OP5	OP6
RS-232	"A"	"A"	"A"	"A"	"A"	"B"
RS-485	"B"	"A"	"B"	"B"	"MDP"	"TRM"
20 mA	"B"	"B"	"A"	"A"	"A"	"C"

[Default]

TABLE "MDP"
FOR RS-485 ONLY

OP5
"A" NORMAL
"B" MULTIDROP

TABLE "TRM"
FOR RS-485 ONLY

OP6
"A" TERMINATED
"B" NOT TERMINATED

2. Open the Micro-Tech wall mount enclosure and turn power off at the mains, or remove panel mount enclosure from the panel and remove top cover allowing access to the mother board.
3. Remove the field mating connector. Wire the connector per the supplied field wiring diagram or install field terminal board cable (wall mount only).
4. Remove the hex head mounting screw from the connector end of the COMM board.
5. Insert the COMM board in any available expansion slot on the mother board (see Figure 2-2).

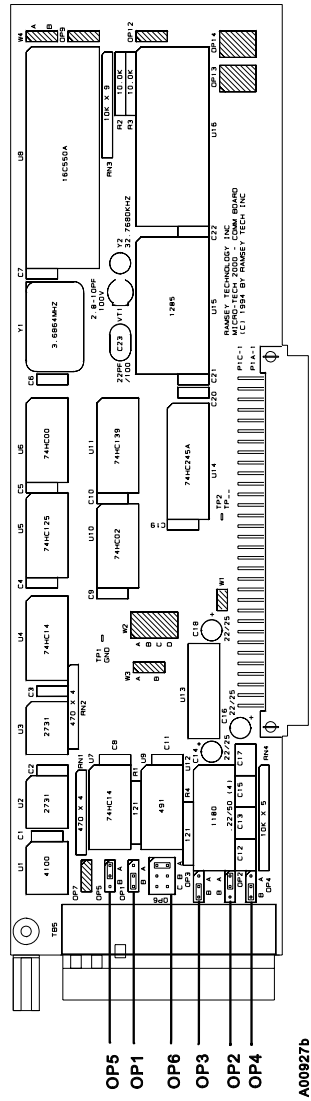
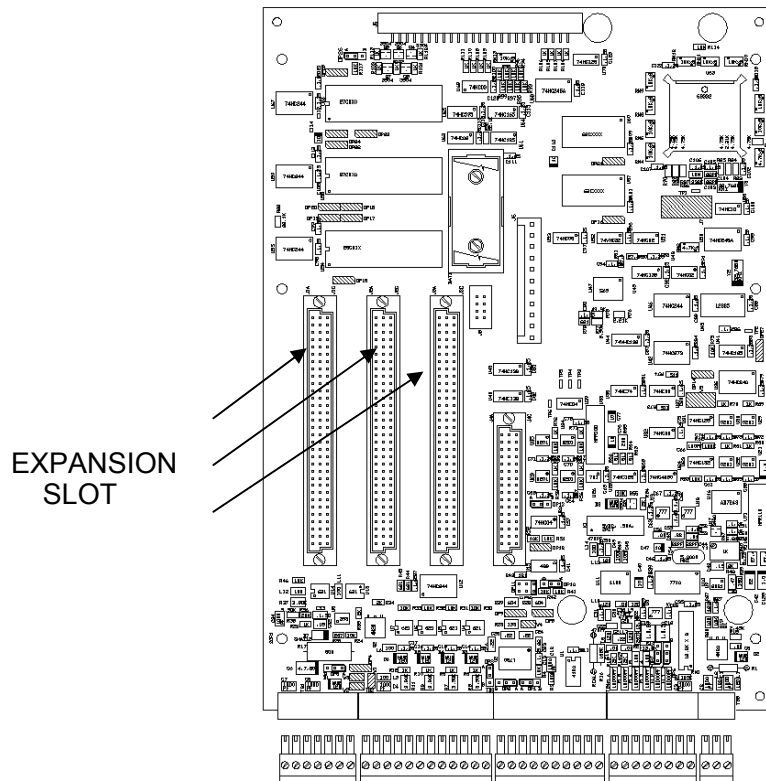


Figure 2-1 COMM A Board

Figure 2-2 Micro-Tech 3000 Mother Board



6. Insert the hex head screw through the chassis and tighten.
7. Install the wired mating connector on the COMM board connector.
8. Reinstall panel mount enclosure in the panel.
9. Turn power back on. The following screen appears when power is applied and remains on for 10 seconds.

-SLOT # N CHANGED
Acquire new
configuration?
YES NO

The screen disappears after 10 seconds if the question is not answered, and the Micro-Tech 3105 assumes the answer is NO. "HW CONFIG. CHANGED" alarm is on and cannot be reset. The above screen appears each time power is cycled if the question is not answered.

Answer YES because this is a hardware configuration change.

10. This completes the installation procedure.
11. Set-up data for the newly installed COMM board must now be entered. Proceed to Chapter 3.0, Operation.

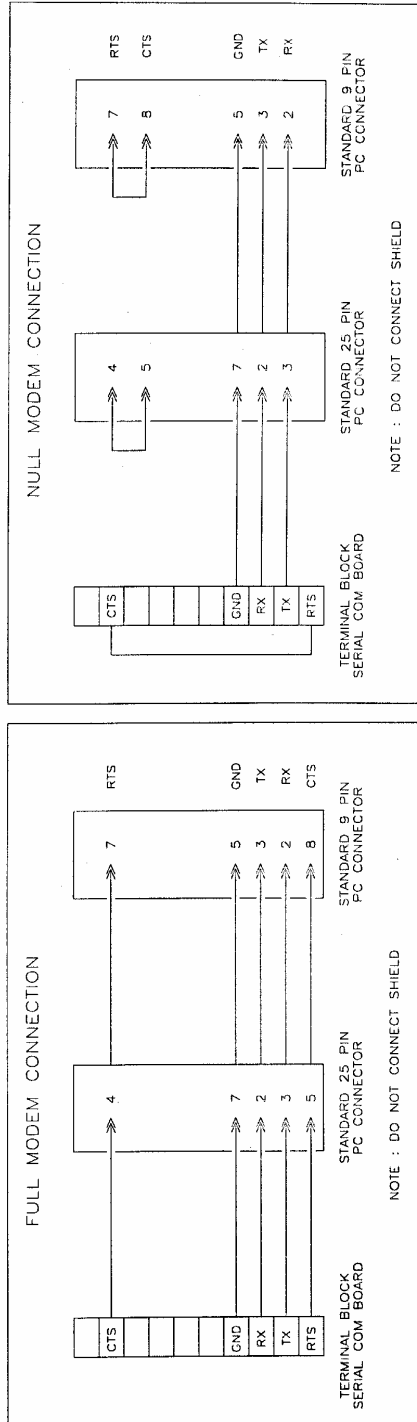


Figure 2-3 Serial Connection RS232

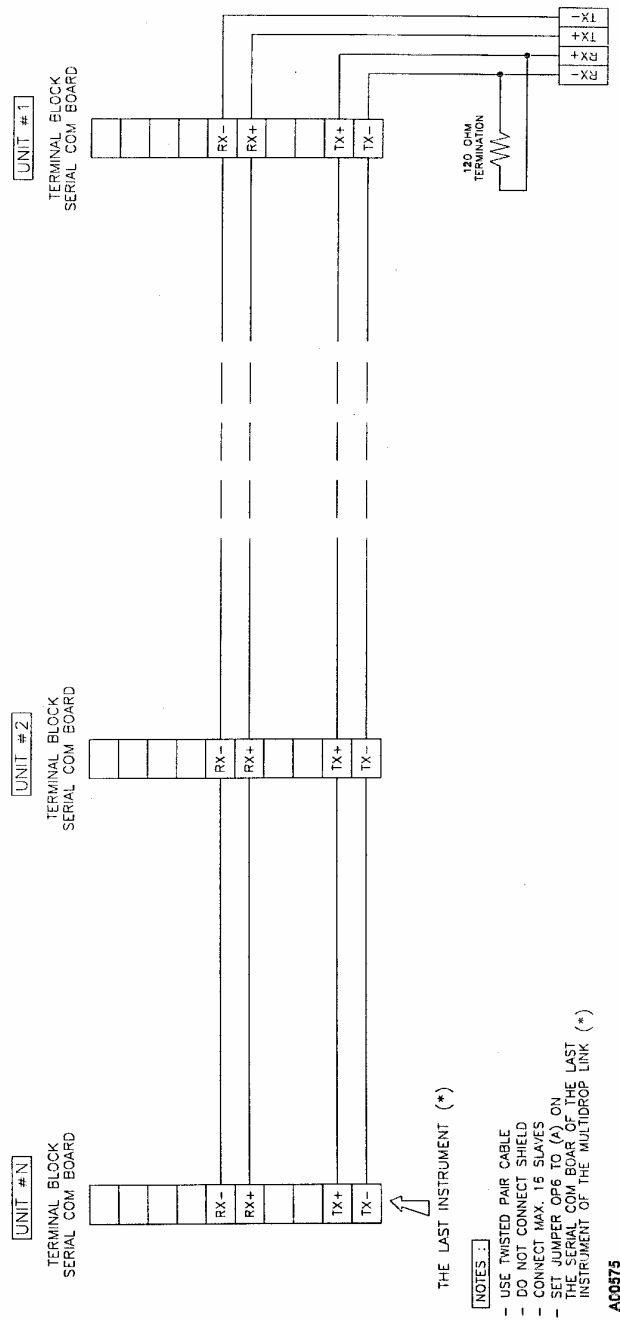


Figure 2-4 Serial Connection RS485

2.3 Communication Configuration (Mother Board) COMM1

This section describes the setup procedure and hardware configuration for the communications from the motherboard. Use the following steps to configure the communications:

Select the jumper positions for the desired communication standard. Refer to Table 2-5 for jumper locations.

Wire to the *Terminal Block 3* on the motherboard for the communication standard selected, *RS-485, RS-232c, 20 mA* current loop.

Table 2-2: Mother Board COMM 1 Communications Wiring Configuration - TB3 – RS-485

Motherboard RS-485 Communications TB 3	
25	Shield
29	-RX
28	+Rx
24	Common
21	+TX
20	-TX

*Maximum cable length 4000 ft
Use Beldon 9830 or equivalent*

Table 2-3: Mother Board Wiring Configuration TB 3 – RS-232 Communications

Motherboard RS-232 Communications TB 3	
25	Shield
23	CTS
24	Common
22	RxD
21	TxD
20	RTS

*Maximum cable length 50 ft
Use Beldon 9538 or equivalent*

Table 2-4: Mother Board Wiring Configuration TB 3 – 20mA Serial Communications

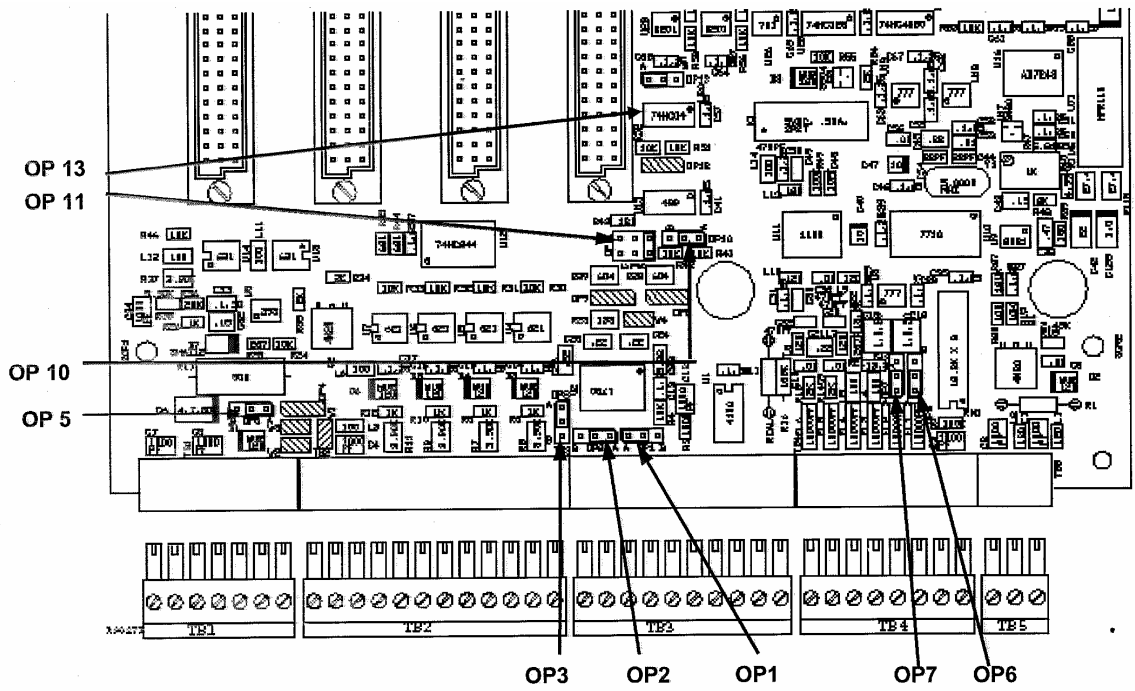
Motherboard 20 mA Serial Communications TB 3	
25	Shield
26	+20 mA (out)
27	-20 mA (out)
28	+20 mA (in)
24	-20 mA (in)

*Maximum cable length 4000 ft
Use Beldon 9829 or equivalent*

Table 2-5: Mother Board Communication Jumper Settings

JUMPERS							
Mode	OP1	OP2	OP3	OP10	OP13	OP11	
RS-485	"A"	"A"	"A"	"A"	"A" Normal "B" Multi-drop	"A" Terminated "B" Not Terminated	Default
RS-232	"B"	"B"	"B"	"A"	"A" Normal	"B" Not Terminated "A" Terminated	Default
20 mA	"A"	"A"	"A"	"B"	"A"	"C"	

Figure 2-5: Mother Board Area of Detail



Chapter 3 Operation

3.1 General

The Micro-Tech 3105 Belt Feeder Controller is a bus-based menu driven machine that allows the operator easy access to all communication and printer set-up scrolls. Main Menu 3's Diagnostic Scroll contains the clock/calendar set-up screens. Main Menu 2's Display Scroll contains the clock/calendar configuration screens, and Main Menu 5 contains the communications and printer set-up scrolls.

The PRINT key enables the Micro-Tech 3105 to print the data selected in the Printer Scroll. Periodical printing and alarms print when directed by the system if enabled.

3.2 Print Formats

The printer can be set up to print totals, batch reports, instrument set-up data, and audit trails upon request. Batch reports and audit trails require optional hardware. In addition, totals can be printed at four predetermined intervals and enabled alarms at the time they occur.

3.2.1 Totals

There are three formats for printing totals; two of them are predefined, one is user programmable. Selection between the different formats is done via menus, as described in the next paragraphs.

The first predefined format is named **DEFAULT1**, and prints data in the following way:

TOTALS REPORT

DATE: 09-10-2002

TIME: 8:12a

MASTER TOTAL: 0.00 Tons

RESET TOTAL: 0.00 Tons

OPERATOR TOTAL: 0.00 Tons

RATE: 0.00 Tph

The second predefined format is named **DEFAULT2**, and prints data in the following way:

DATE: 09-10-2002

TIME: 8:12a

MASTER START TOTAL: 0.00 Tons

RESET STOP TOTAL: 0.00 Tons

QUANTITY: 0.00 Tons

In both cases, the format in which date and time are printed depends on the system set-up.

The last method called **USER DEFINED**, is to define your own format using the printer set up screens as described in Section 3.3.4.

The USER DEFINED format includes three programmable strings and a mean of printing the average rate during totalization. The position of each datum on the paper can be assigned by row and column, making it easy to fulfill any custom requirement.

3.2.2 Batch

If the optional Load Out board is installed, the load out data can be printed in the following format:

BATCH REPORT

DATE: 09-10-2002

TIME: 8:12a

BATCH NR: 0

SET PT: 0.00 Tons

TOTAL : 0.00 Tons

3.2.3 Alarms

The system can optionally print out each alarm (if the alarm has been turned on in the Alarms Menu) in the following format:

09-10-2002 8:14a

High rate

where "High rate" is only an example of a possible alarm condition. Date and time corresponds to when the alarm has occurred the first time.

3.2.4 Set-Up

The entire system set-up data can be printed by the unit for the customer's record. Format and sequence of data can vary depending on the hardware and software configurations.

3.2.5 Audit Trails

When Audit Trails is installed, the recorded data can be printed out in the following format:

TRAIL RECORD NR 1

DATE 09-10-2002 TIME 11:59p

VARIABLE scale cap

NEW 400.00

OLD 500.00

TRAIL RECORD NR 2
DATE 09-10-2002 TIME 11:31p
VARIABLE span
NEW 250000
OLD 300000

TRAIL RECORD NR 3
DATE 09-10-2002 TIME 11:59p
VARIABLE div (e)
NEW 0.05
OLD 0.1

Each record contains a description of the variable which has been altered, the old and the new values of the variable, and an index number.

3.3 Communication Set-Up

This section explains the communication and printer set-up. See Section 3.4 for communication protocols detailed description.

3.3.1 Clock/Calendar Set-Up

When an COMM A board is installed, date and time become available and must be set. The battery, located on the mother board, provides backup for the perpetual calendar/clock. Time and date needs to be set only once.

1. Press the MENU key until Main Menu 3 appears. Press the soft key under the DIAGNOSTICS scroll and scroll down until -DIAGNOST SCROLL 7- appears.

The following scroll is provided to set up the date, and enter the day, month and year in sequence.

<p>-DIAGNOST. SCROLL 7- Date: DD-MM-YYYY DAY: DD ENTER</p>
--

Password : SERVICE

Default: 00-00-0000
Min: 01-01-0000
Max: 12-31-2002

Time is entered in a similar way. The **AM/PM** key is used when time is in the English mode (see Display Scroll 7 below).

-DIAGNOST. SCROLL 8-
Time: HH:MM
HOURS: HH
ENTER AM/PM

Password: SERVICE

24 hour am/pm
Default: 00:00 01:00
Min: 00:00 01:00
Max: 23:59 12:59

2. Press the MENU key until Main Menu 2 appears. Press soft key under DISPLAY scroll and scroll down until -DISPLAY SCROLL 7- appears.

The user can define the format for displaying and printing time and date. Select the 24 hours or 12 hours format:

- DISPLAY SCROLL 7 -
Time
> 24 h <
CHOICE ENTER

Password: Service

If USA or English: Default: am/pm
If other language: Default: 24 h
Selections: am/pm, 24 h

Then date can be set to show month or day first, in three possible configurations:

- DISPLAY SCROLL 8 -
Date
> DD-MM-YYYY <
CHOICE ENTER

Password: Service

If USA: Default: MM-DD-YYYY
If other language: Default: DD-MM-YYYY
Selections: DD-MM-YYYY, MM-DD-YYYY, YYYY-MM-DD

3. When a COMM board is installed, date and time can be displayed line three (3) in the RUN screen if selected using DISPLAY SCROLL 9.

- DISPLAY SCROLL 9 -
Run display line 3
> No Display <
CHOICE ENTER

Password: Service

Default: NO DISPLAY
Selections: NO DISPLAY, LOAD, SPEED, DATE/TIME

3.3.2 COMM A and Print Scroll Set-Up

Main Menu 5 is dedicated to the serial line. COMM A is used to set up the serial line of the COMM A , regardless if the serial line is connected to a computer or a PLC or for printing. The PRINT scroll is used for setting up the printer, and it only appears if the COMM A is set for printer.

```

- MAIN MENU 5 -
Press MENU for more

COMM A   PRINT
    
```

1. Line Setting and Protocol Definition

Two COMM line can be installed and programmed, typically one for the printer and one for the supervisor.

The following screens define the communication parameters for the first and the second channel.

```

- COMM. A SCROLL 1 -
  Baud rate port #1
> 2400 <
CHOICE ENTER
    
```

Password: Service

Default: 9600

Selections: 110, 150, 300, 600, 1200, 2400, 4800, 9600, 19200

```

- COMM. A SCROLL 2 -
  Set parity port #1
> No parity <
CHOICE ENTER
    
```

Password: Service

Default: NO PARITY

Selections: EVEN PARITY, ODD PARITY, NO PARITY

```

- COMM. A SCROLL 3 -
  Stop bits port #1
> 1 <
CHOICE ENTER
    
```

Password: Service

Default: 1

Selections: 1,2

```

- COMM. A SCROLL 4 -
  Wordlength port #1
> 8 <
CHOICE ENTER
    
```

Password: Service

Default: 8

Selections: 7,8

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The next screen defines the port use. Some commonly used protocols are implemented in the system. Possible selections are:

- PC-MASTER Ramsey proprietary protocol: Multidrop, Master Slave.
- SIEMENS 3964R A proprietary protocol of Siemens. Point to point, Multi Master.
- ALLEN-BRADLEY A proprietary protocol of Allen-Bradley.
DF1 Multidrop, Master Slave.
- MODBUS A proprietary protocol of AEG. Multidrop, Master Slave.
- PRINTER Not a protocol, selects printer output.

- COMM. A SCROLL 5 -
Protocol port #1
> MODBUS <
CHOICE ENTER

Password: Service

- Default: MODBUS
- Selections: PC-MASTER, SIEMENS 3964R, ALLEN-BRADLEY DF1, MODBUS, PRINTER

If the option COMM A board is installed, the following screen appears. These screens operate exactly as the ones dedicated to the COMM A on the Mother Board.

- COMM. A SCROLL 8 -
Baud rate port #2
> 2400 <
CHOICE ENTER

Password: Service

- Default: 9600
- Selections: 110, 150, 300, 600, 1200, 2400, 4800, 9600, 19200

- COMM. A SCROLL 9 -
Set parity port #2
> No parity <
CHOICE ENTER

Password: Service

- Default: NO PARITY
- Selections: EVEN PARITY, ODD PARITY, NO PARITY

- COMM. A SCROLL 10 -
Stop bits port #2
> 1 <
CHOICE ENTER

Password: Service

- Default: 1
- Selections: 1,2

```

- COMM. A SCROLL 11 -
Wordlength port #2
> 8 <
CHOICE ENTER
    
```

Password: Service

Default: 8
 Selections: 7,8

```

- COMM. A SCROLL 12 -
Protocol port #2
> PRINTER <
CHOICE ENTER
    
```

Password: Service

Default: PRINTER
 Selections: PC-MASTER, SIEMENS 3964R, ALLEN-BRADLEY DF1, MODBUS, PRINTER

3.3.3 Multidrop Operator Set-Up

NOTE: This section only applies to multidrop operation. If you are using the COMM for connecting a printer, skip this section and refer to Section 3.3.4. The Clear To Send (CTS) line of the port can be used for hardware handshake. Select Enabled if you want to connect the CTS input of the system to a control signal generated by the other device.

WARNING

THE CTS INPUT CAN ONLY BE USED WHEN JUMPERS ARE SET FOR RS232. ATTEMPTING TO ENABLE THE CTS SOFTWARE CONTROL IN RS485 MODE WILL RESULT IN LOCK-UP OF THE LINE.

```

- COMM. A SCROLL 5A -
Clear to Send #1
> Disabled <
CHOICE ENTER
    
```

Password: Service

Default: DISABLED
 Selections: ACTIVE, DISABLED

The following screens define the ADDRESS of the device in the multidrop line, and the access permission from the remote supervisor. If NONE is selected, the supervisor has full access to the device. If LIMITED is selected, the supervisor can only access those variables that are accessible with the OPERATOR password. If PROTECTED is selected, the unit is read only to the supervisor.

```

- COMM. A SCROLL 6 -
Address port #1
> 1 <
ENTER
    
```

Password: Service

Default: 1
 Min: 1
 Max: 255

- COMM. A SCROLL 7 -
Access prot port #1
> None <
CHOICE ENTER

Password: Service

Default: NONE
Selection: NONE, LIMITED, PROTECTED

Similarly for COMM 2, if installed:

- COMM. A SCROLL 12A -
Clear to Send #2
> Disabled <
CHOICE ENTER

Password: Service

Default: DISABLED
Selections: ACTIVE, DISABLED

- COMM. A SCROLL 13 -
Address port #2
> 1 <
ENTER

Password: Service

Default: 1
Min: 1
Max: 255

- COMM. A SCROLL 14 -
Access prot port #2
> None <
CHOICE ENTER

Password: Service

Default: NONE
Selection: NONE, LIMITED, PROTECTED

3.3.4 Printer Set-Up

NOTE: This section only applies to printer. If you are using the COMM for connecting a computer, PLC or other device using a protocol, skip this section and refer to Section 3.3.3.

The Micro-Tech 3105 has a fully programmable printer format. The following section explains how to program the Print scroll according to the specific needs.

The system can be configured to operate without any handshake (NONE), or using the Clear To Send signal (CTS) or the XON-XOFF sequence. Refer to the instruction manual of the printer to define which selection is required. The selection NONE is only supplied for testing purposes, but is not recommended for normal use. If NONE is selected, the system is not able to recognize if the printer is on line or not, or if the paper is empty.

The most commonly used protocol is the CTS, which is a signal generated by the printer to indicate whether it is ready to receive data or not.

WARNING

THE CTS INPUT CAN ONLY BE USED WHEN JUMPERS ARE SET FOR RS232. ATTEMPTING TO ENABLE THE CTS SOFTWARE CONTROL IN RS485 MODE WILL RESULT IN LOCK-UP OF THE LINE.

**- PRINTER SCROLL 1 -
Handshaking
> None <
CHOICE ENTER**

Password: Service

Default: NONE
Selection: NONE, CTS, XON-XOFF

Different printers use different end of line patterns. Select the one you need according to the printer.

**- PRINTER SCROLL 2 -
End of line
> CR <
CHOICE ENTER**

Password: Service

Default: CR
Selection: CR, LF, CR+LF

Some simple printers cannot accept characters while they are printing. In some cases the handshake is not well controlled by the printer, so a delay at end of line is helpful.

**- PRINTER SCROLL 3 -
Delay end of line
0 sec
ENTER**

Password: Service

Default: 0 sec
Min: 0 sec
Max: 5 sec

A Form Feed character can be sent to the printer after each report to force the printer to eject the paper.

**- PRINTER SCROLL 4 -
Form Feed
> NO <
CHOICE ENTER**

Password: Service

Default: NO
Selections: NO, YES

If you want to generate periodical printing, enter the number of minutes, hours or days in the following screen. By entering 0, the periodical printing is prevented. Use the INTV key to switch from minutes to hours and to days.

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- PRINTER SCROLL 5 -
Print interval
0 min
ENTER INTV

Password: Service

Default: 0
Min: 0 min, 0 hour, 0 days
Max: 59 min, 23 hour, 365 days

The system can print at specific times during the day. Enter the time you want to obtain the printing. Use the NEXT keys to scroll between the print times. Up to four discrete times may be entered. The ON/OFF key enables or disables the displayed print time.

- PRINTER SCROLL 6 -
Print time # 1
time HH:MM
ENTER ON/OFF NEXT

Password: Operator

Default: OFF
Min: 00:00
Max: 23:59

3.3.5 Define Printing Format

By selecting YES in the following screen, the system is instructed to print one line each time a new alarm condition occurs. The alarm is printed as follows:

xx-xx-xxxx yy:yyz
kkkkkkkkkkkkkkkkkkkkkk

where:

xx-xx-xxxx	Day, Month, Year, printed according to the local format as defined in Main Menu 2 - Display.
yy:yyz	Hour, Minutes, am/pm printed according to the local format as defined in Main Menu 2 - Display
kkkkkkkkkkkkkkkkkkkkkk	Alarm message, same message appearing on the screen.

For example:

09-10-2002 8:14a
High rate

- PRINTER SCROLL 7 -
Print alarms
> No <
CHOICE ENTER

Default: NO
Selections: NO, YES

If YES is selected, the system prints all alarms that have been set to alarm in the Alarm scroll.

There are three ways for defining the printing format. The first two are predefined formats, which are as follows:

1. DEFAULT 1
TOTALS REPORT

DATE: 09-10-2002
TIME: 8:12a

MASTER TOTAL: 0.00 Tons
RESET TOTAL: 0.00 Tons
OPERATOR TOTAL: 0.00 Tons
RATE: 0.00 Tph

2. DEFAULT 2

DATE: 09-10-2002
TIME: 8:12a

MASTER START TOTAL: 0.00 Tons
RESET STOP TOTAL: 0.00 Tons
QUANTITY: 0.00 Tph

3. Define Own Format

The last method is to define your own format using the printer setup screens listed below.

Select DEFAULT if you want the predefined format. Select USER DEFINED if you want to set up your own format.

```
- PRINTER SCROLL 8 -  
Totals Report format  
> Default <  
CHOICE ENTER
```

Password: Service

Default: DEFAULT1
Selections: DEFAULT1, DEFAULT2, USER DEFINED

If your selection is USER DEFINED, the following screens are displayed.

Define first the number of strings that you want to add in your report. You may enter a number from 0 to 3. Strings can be used to add the Customer name as well as other information that you want to include in the print format.

```
- PRINTER SCROLL 9A -  
Number of strings  
> 3 <  
ENTER
```

Password: Operator

Default: 1
Min: 0
Max: 3

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If you specified a number of strings larger than zero, you can now enter the strings. Use the alphanumeric keypad, pressing the numeric key corresponding to the letter that you want to type. Each time you press a new key, the cursor moves to the right one place. If you need to use the same key twice (example: for double letters), move the cursor right using the arrow keys (left and right soft keys).

```

- PRINTER SCROLL 9B -
  Contents strings #1
  XXXXXXXXXXXXXXXXXXXXX
  <  ENTER  >
    
```

Password: Operator

Default: XXXXXXXXXXXXXXXXXXXXX

Once you have defined the string, you have to specify where the string is to be placed on the printed report. The coordinate is given in the following way:

```

000000000011111111112222222223...
0123456789012345678901234567890...
+-----> Y
00|This line printed first
01|This line printed second           ^
02|                                   | DIRECTION OF
03|                                   | PAPER
04|
05|
06|
. v
. X
    
```

Use the X-pos and Y-pos keys to enter the X and Y coordinates. Confirm with **ENTER**. By specifying 0,0, the string is not printed.

```

- PRINTER SCROLL 9C -
  Position string #1
  X = 0 ,        Y = 0
  ENTER X-pos  Y-pos
    
```

Password: Operator

Default: 1,1
 Min: 0,1
 Max: 24,80

If you specified more strings, enter the relevant data using the same procedure.

```

- PRINTER SCROLL 9D -
  Contents strings #2
  XXXXXXXXXXXXXXXXXXXXX
  <  ENTER  >
    
```

Password: Operator

Default: XXXXXXXXXXXXXXXXXXXXX

- PRINTER SCROLL 9E -
Position string #2
X = 0 , Y = 0
ENTER X-pos Y-pos

Password: Operator

Default: 2,1
Min: 0,1
Max: 24,80

- PRINTER SCROLL 9F -
Contents strings #3
XXXXXXXXXXXXXXXXXXXX
< ENTER >

Password: Operator

Default: XXXXXXXXXXXXXXXXXXXX

- PRINTER SCROLL 9G -
Position string #3
X = 0 , Y = 0
ENTER X-pos Y-pos

Password: Operator

Default: 3,1
Min: 0,1
Max: 24,80

- PRINTER SCROLL 9H -
Position oper. total
X = 0 , Y = 0
ENTER X-pos Y-pos

Password: Operator

Default: 4,1
Min: 0,1
Max: 24,80

In a similar way, you can position in the print format the following variables:

The Reset Total:

- PRINTER SCROLL 9I -
Position reset total
X = 0 , Y = 0
ENTER X-pos Y-pos

Password: Operator

Default: 5,1
Min: 0,1
Max: 24,80

The Master Total:

- PRINTER SCROLL 9J -
Position master total
X = 0 , Y = 0
ENTER X-pos Y-pos

Password: Operator

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Default: 6,1
Min: 0,1
Max: 24,80

The Current Date:

- PRINTER SCROLL 9K -
Position date
X = 0 , Y = 0
ENTER X-pos Y-pos

Password: Operator

Default: 7,1
Min: 0,1
Max: 24,80

The Current Time:

- PRINTER SCROLL 9L -
Position time
X = 0 , Y = 0
ENTER X-pos Y-pos

Password: Operator

Default: 8,1
Min: 0,1
Max: 24,80

The Instantaneous Value of Rate::

- PRINTER SCROLL 9M -
Position RATE
X = 0 , Y = 0
ENTER X-pos Y-pos

Password: Operator

Default: 9,1
Min: 0,1
Max: 24,80

The Average Rate since the last print is next. The average rate is calculated only on the periods of time in which rate has been higher than 5% of capacity.

- PRINTER SCROLL 9N -
Position AVG RATE
X = 0 , Y = 0
ENTER X-pos Y-pos

Password: Operator

Default: 0,1
Min: 0,1
Max: 24,80

The running time since the last print. The running time is the time in which rate has been higher than 5%.

```

- PRINTER SCROLL 9P -
Position RUNNING TM
X = 0 ,      Y = 0
ENTER X-pos  Y-pos
    
```

Password: Operator

Default: 0,1
 Min: 0,1
 Max: 24,80

If the optional load out board is installed, the batch quantity and the batch total can also be printed.

3.3.6 Setting the Printer Inhibit Range

The Printer Inhibit Range setting prevents printing when the rate is higher than a preset value. This is a requirement of NTEP, and therefore automatically turned on when the NTEP W&M mode is selected.

```

- PRINTER SCROLL 12P -
Print Inhibit range
0%
ENTER
    
```

Password: Service

Default: 3%
 Min: 0%
 Max: 100%

3.3.7 The Print Key

This section only applies to the Printer. If you are using the COMM for connecting a computer or a PLC and you are using a protocol, skip this section and refer to Section 3.3.2.

The Micro-Tech 3105 can print out several kinds of data, depending on the system set-up. When the printer has been installed and properly set up, the user can print by means of the PRINT key as described below.

When the PRINT key is pressed, the following screen is displayed:

```

- PRINTER SCROLL -
COM #1 no data
Start print TOTALS
PRINT RETURN COM
    
```

Password: Not Required

The second line gives the status of the printer:

NO DATA Indicates the printer is idle, no data is being sent to the printer.
 IS RUNNING Indicates the system is sending data to the printer.

The third line indicates what kind of data is printed if the PRINT soft key is pressed.

The UP and DOWN keys select between:

- a. TOTALS Prints the selected totals format. Default1, Default2, or User Define (see Section 3.3.5).
- b. BATCH Only if load out option is active, print load out information.

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- c. SETUP Print the set-up data of the instrument.
- d. TRAILS If audit trails option is active, print audit trails data. (See Main Menu 6 in the Micro-Tech 3000 manual.)

Print starts after the PRINT soft key is pressed.

The COM key allows the operator to select the printer if more than one is installed.

3.3.8 Additional Diagnostic

If a Communication board is detected, the following screen is shown. The "Port 2" soft key is only shown if two boards are detected.

- TEST SCROLL 8 -	
Test communication A	
PORT1	PORT2

Password: Service

By pressing the PORT 1 or the PORT 2 soft key the test is initiated. A test pattern is sent out on the TX output and read on the RX input. If the test fails, the message TEST FAILED is shown, otherwise the message TEST PASSED is displayed.

NOTE: This test requires a hardware jumper to be installed between the (RX) and (TX) terminals of the communication board.

3.4 Communication Protocols

The communication protocol allows a remote intelligent device to read and eventually write the contents of the registers as listed in this section.

During the communication activity, the Micro-Tech 3105 always acts as Slave, meaning that it will respond to a request from a Master device on the line, but never attempts to send messages out.

The instrument responds only if the message is completely received. The instrument reads the message and looks for the address, which is contained in an address byte in the query package. The message is then processed only if the address contained in the message matches the address specified in the set-up data of the instrument. When the system receives a message, the integrity of it is checked, and an answer message is prepared if yes.

The Master must respect a 100 ms interval time between two messages. If a message is sent before 100 ms have passed since the previous one, it is lost. (The data is received by an interrupt routine, while it is processed in a task which is executed each 100 ms.)

If the Master sends variables to be written in memory, the system checks the correctness of the message, and immediately sends an answer message if it is correct. This does not necessarily mean that the data is written in memory. The system first checks the address, which must correspond to a valid address of a variable, then the minimum and maximum limits are checked, and then the password. If data can be accepted, the success flag is set to 0 (no error), if not, it is set to 1. The Master needs to check the success flag (contained into a read only register), to know if the last variables sent have been stored or not.

The procedure is as follows:

- Send the data to the Micro-Tech 3105
- Wait 100 ms
- Read the success flag, should be 0.

Some data is read only, some is read write, some is write only.

NOTE: The maximum number of words the system can transfer is 41 per time. Requests of registers in excess of 41 are treated as errors and do not generate an answer.

NOTE: This section only applies to multidrop operation. If you are using the COMM option for connecting a Printer, skip this section and refer to Section 3.3.4.

3.4.1 Register Definition

The following registers can be accessed through a serial line link using one of the available communication protocols. The table lists the registers specifying per each:

- register	A conventional name		
- type	Can be:	RO	The register can be read but cannot be written.
		RW	The register can be read or written. Write is allowed if the instrument is in the specified protection level at the moment the write message is received.
		WO	The register can only be written. Write is subject to protection control.
- low limit	The minimum acceptable value for the variable. Lower values are considered as errors.		
- high limit	The maximum acceptable value for the variable. Higher values are considered as errors.		
- refresh time	The time between two updates of the variable in the instrument's memory.		
- protection	The minimum protection level which must be in place to allow access to the variable:		
	- always available		
	limited	available if limited or service	
	service	available if service only	
- format	Can be:	char	An ASCII string
		integer	16 bits IEEE integer
		float	32 bits IEEE float
		double	64 bits IEEE float
		long	32 IEEE integer

WARNING

THE ACTUAL ADDRESS OF EACH REGISTER IS DEFINED DIFFERENTLY FOR EACH PROTOCOL AS EXPLAINED IN THE FOLLOWING SECTIONS.

1. Type, Limits and Format of Register

register	type	low limit	high limit	Refresh Time [ms]	protection	format
success_flag	RO	-	-	-	none	integer
display	RO	-	-	100	-	char
leds	RO	-	-	100	-	integer
status	RO	-	-	100	-	integer
alarms	RO	-	-	100	-	integer
i_o	RO	-	-	100	-	integer
commands	WO	0	32767	100	none	integer
rate	RO	-	-	100	-	float
load	RO	-	-	100	-	float
speed	RO	-	-	100	-	float
master_total	RO	-	-	100	-	float
reset_total	RW	0 (1)	0 (1)	100	none	float
operator_total	RW	0 (1)	0 (1)	100	limited	float
batch_total	RO	-	-	100	-	float
batch_number	RW	0	999	100	limited	integer
batch_set	RW	0	10000	-	limited	float
batch_pre_set	RW	0	10000	-	limited	float
batch_pre_act	RW	0	10000	-	limited	float
batch_deviation	RW	0	100	-	limited	integer
scale_capacity	RW	1	200000	-	service	float
speed_capacity	RW	0.1m/s or 1 fpm	10 m/s or 2000 fpm	-	service	float
Percent of Ingrid. 1	rw	0%	100.0%		limited	float
Percent of Ingrid. 2	rw	0%	100.0		limited	float
batch_pre_set	rw	0.0%	100.0%		limited	float
reg_set_point_1	RW	0	20000.0	-	limited	float
reg_set_point_2	RW	0	20000.0	-	limited	float
dsp_set_point_1	RO	-	-	100mS	-	float
dsp_set_point_2	RO	-	-	100mS	-	float
ctr_deviation_1	RO	-	-	100mS	-	float
ctr_deviation_2	RO	-	-	100mS	-	float
hi_pos_dev_1	RW	0%	105%	-	limited	float
hi_hi_pos_dev_1	RW	0%	105%	-	limited	float
hi_neg_dev_1	RW	0%	105%	-	limited	float

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register	type	low limit	high limit	Refresh Time [ms]	protection	format
hi_hi_neg_dev_1	RW	0%	105%	-	limited	float
hi_pos_dev_2	RW	0%	105%	-	limited	float
hi_hi_pos_dev_2	RW	0%	105%	-	limited	float
hi_neg_dev_2	RW	0%	105%	-	limited	float
hi_hi_neg_dev_2	RW	0%	105%	-	limited	float
cal_error	RO	-	-	-	none	float
span	RO	-	-	-	none	float
zero	RO	-	-	-	none	long
azt_correction	RO	-	-	-	none	float
master total	RO	-	-	-	none	double
reset total	RO	-	-	-	none	double
operator total	RO	-	-	-	none	double
out analogic	RO			-	-	float
Prop. Band	RW	50%	1000	-	limited	integer
Integral Time	RW	0 min	10 min	-	limited	float
Deriv. Time	RW	0 min	10 min	-	limited	float
Set cont. Value	RW	0	100%	-	limited	integer
Regulat. delay	RW	0	900 sec	-	limited	integer
Var. 1 damping	RW	0	120 sec	-	limited	integer
Var. 2 damping	RW	0	120 sec	-	limited	integer

- (1) Can only be zeroed.
- (2) Max load defined as :

$$\text{Max load} = \frac{\text{Cap_cell} * \text{cell number}}{\text{Idler spacing} * \text{of weigh idlers}}$$

2. Description of Register

In the following section an explanation is given per each variable of the above table.

a. success_flag

Set to 0 after a message has been received and properly processed. If a message is correctly received but cannot be processed because password protection or size error, this flag is set to 1. The user may read this register after a write message to ensure the data have been accepted.

b. display

It contains the messages actually shown on the display of the instrument in form of an ASCII string. For example, the screen:

- MENU MAIN 1 -		
PRESS MENU FOR MORE		
ZERO	SPAN	MAT'L
CAL	CAL	CAL

Will be stored in registers in the following way:

display(1)	2DH	20H	Characters 1 and 2 from left of first row
display(2)	4DH	45H	
display(3)	4EH	55H	
display(4)	20H	4DH	
display(5)	41H	49H	
display(6)	4EH	20H	
.....			
display(10)	Characters 19 and 20 from left of first row
display (11)	Characters 1 and 2 from left second row
.....			
display(20)	Characters 19 and 20 from left of second row
display(21)	Characters 1 and 2 from left of third row
.....			
display(30)	Characters 19 and 20 from left of third row
display(31)	Characters 1 and 2 from left of fourth row
.....			
display(38)	4CH	20H	
display(39)	20H	20H	
display(40)	20H	20H	Characters 19 and 20 from left of fourth row

c. leds

Leds(1)	bit	description
	15	not used
	05	not used
	04	led 5 (1 = on, 0 = off)
	03	led 4
	02	led 3
	01	led 2
	00	led 1

d. status

Status(1)	bit	description
	15	cumulative shutdown (a shutdown alarm is pending)
	14	cumulative alarms (an alarm is pending)
	13	calibration running
	12	remote (1) local (0)
	11	automatic (1) manual (0)
	10-8	Not used
	07	High load (Load is higher than limit)
	06	Low load (Load is lower than limit)
	05	High rate (Rate is higher than limit)
	04	Low rate (Rate is lower than limit)
	03	High speed (Speed is higher than limit)
	02	Low speed (Speed is lower than limit)
	01-0	Not used

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Status(2)	<u>bit</u>	<u>description</u>
	15	high pos deviation #1
	14	high high pos deviation #1
	13	high neg deviation #1
	12	high high neg deviation #1
	11	high pos deviation #2
	10	high high pos deviation #2
	09	high neg deviation #2
	08	high high neg deviation #2
	07-04	Not used
	03-00	Only applicable if Load Out option installed :
	3 2 1 0	
	x 0 0 0	Batch not running
	x 0 0 1	Not used
	x 0 1 0	Batch running at high rate
	x 0 1 1	Batch running at low rate
	x 1 0 0	Waiting start delay time
	x 1 0 1	Waiting stabilization time
	x can be	0 Normal status
		1 Stand by status

e. alarms

In the alarms register, each bit represents the status of an alarm. If the alarm is active, the relevant bit contains '1', otherwise it contains '0'.

alarms(1)	<u>bit</u>	<u>description</u>
	15	CLOCK FAIL
	14	CELL FAIL
	13	RAM FAIL
	12	ROM FAIL
	11	SPEED SENSOR ERROR
	10	HIGH LOAD
	09	LOW LOAD
	08	HIGH RATE
	07	LOW RATE
	06	HIGH SPEED
	05	LOW SPEED
	04	WARM START
	03	COLD START
	02	PWD DURING CALIB
	01	CAL TIME ELAPSED
	00	EXTERN ALAM 1

alarms(2)	<u>bit</u>	<u>description</u>
	15	EXTERN ALAM 2
	14	EXTERN ALAM 3
	13	OVERFLOW TOTALIZER
	12	AZT OVER LIMIT
	11	BATCH DEVIATION
	10	HW CNF CHANGE SLOT 1
	09	HW CNF CHANGE SLOT 2
	08	W CNF CHANGE SLOT 3
	07	
	06	
	05	
	04	BCD OVERFLOW

03	MATHEMATIC ERROR
02	PRINTER ERROR
01	COMMUNICATION ERROR
00	NOT USED

alarms(3)	<u>bit</u>	<u>description</u>
	15-09	NOT USED
	09	HIGH POS DEVIATION #1
	07	HIGH HIGH POS DEVIATION #1
	06	HIGH NEG DEVIATION #1
	05	HIGH HIGH NEG DEVIATION #1
	04	HIGH POS DEVIATION #2
	03	HIGH HIGH POS DEVIATION #2
	02	HIGH NEG DEVIATION #2
	01	HIGH HIGH NEG DEVIATION #2
	00	NOT USED

f. i_o

The instrument has physical inputs and outputs to which logical input and output functions are associated. As far as communication is concerned, only the status of physical inputs and outputs are transferred.

i_o(1)	<u>bit</u>	<u>description</u>
	15-04	not used
	03	in 3 – mother board
	02	in 2 – mother board
	01	in 1 – mother board
	00	in 0 – mother board

i_o(2)	<u>bit</u>	<u>description</u>
	15	in 3 board 4in/16out # 1
	14	in 2 board 4in/16out # 1
	13	in 1 board 4in/16out # 1
	12	in 0 board 4in/16out # 1
	11	in 3 board 4in/16out # 2
	10	in 2 board 4in/16out # 2
	09	in 1 board 4in/16out # 2
	08	in 0 board 4in/16out # 2
	07	in 3 board 4in/16out # 3
	06	in 2 board 4in/16out # 3
	05	in 1 board 4in/16out # 3
	04	in 0 board 4in/16out # 3
	03	in 3 board 4in/16out # 4
	02	in 2 board 4in/16out # 4
	01	in 1 board 4in/16out # 4
00	in 0 board 4in/16out # 4	

i_o(3)	<u>bit</u>	<u>description</u>
	15	in 15 board 16in/4out # 1
	14	in 14 board 16in/4out # 1
	13	in 13 board 16in/4out # 1
	12	in 12 board 16in/4out # 1
	11	in 11 board 16in/4out # 1

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10	in 10	board 16in/4out # 1
09	in 09	board 16in/4out # 1
08	in 08	board 16in/4out # 1
07	in 07	board 16in/4out # 1
06	in 06	board 16in/4out # 1
05	in 05	board 16in/4out # 1
04	in 04	board 16in/4out # 1
03	in 03	board 16in/4out # 1
02	in 02	board 16in/4out # 1
01	in 01	board 16in/4out # 1
00	in 00	board 16in/4out # 1

<u>i_o(4)</u>	<u>bit</u>	<u>description</u>
	15	in 15 board 16in/4out # 2
	14	in 14 board 16in/4out # 2
	13	in 13 board 16in/4out # 2
	12	in 12 board 16in/4out # 2
	11	in 11 board 16in/4out # 2
	10	in 10 board 16in/4out # 2
	09	in 09 board 16in/4out # 2
	08	in 08 board 16in/4out # 2
	07	in 07 board 16in/4out # 2
	06	in 06 board 16in/4out # 2
	05	in 05 board 16in/4out # 2
	04	in 04 board 16in/4out # 2
	03	in 03 board 16in/4out # 2
	02	in 02 board 16in/4out # 2
	01	in 01 board 16in/4out # 2
	00	in 00 board 16in/4out # 2

<u>i_o(5)</u>	<u>bit</u>	<u>description</u>
	15	in 15 board 16in/4out # 3
	14	in 14 board 16in/4out # 3
	13	in 13 board 16in/4out # 3
	12	in 12 board 16in/4out # 3
	11	in 11 board 16in/4out # 3
	10	in 10 board 16in/4out # 3
	09	in 09 board 16in/4out # 3
	08	in 08 board 16in/4out # 3
	07	in 07 board 16in/4out # 3
	06	in 06 board 16in/4out # 3
	05	in 05 board 16in/4out # 3
	04	in 04 board 16in/4out # 3
	03	in 03 board 16in/4out # 3
	02	in 02 board 16in/4out # 3
	01	in 01 board 16in/4out # 3
	00	in 00 board 16in/4out # 3

<u>i_o(6)</u>	<u>bit</u>	<u>description</u>
	15	in 15 board 16in/4out # 4
	14	in 14 board 16in/4out # 4
	13	in 13 board 16in/4out # 4
	12	in 12 board 16in/4out # 4
	11	in 11 board 16in/4out # 4
	10	in 10 board 16in/4out # 4

09	in 09	board 16in/4out # 4
08	in 08	board 16in/4out # 4
07	in 07	board 16in/4out # 4
06	in 06	board 16in/4out # 4
05	in 05	board 16in/4out # 4
04	in 04	board 16in/4out # 4
03	in 03	board 16in/4out # 4
02	in 02	board 16in/4out # 4
01	in 01	board 16in/4out # 4
00	in 00	board 16in/4out # 4

i_o(7)	<u>bit</u>	<u>description</u>
	15-04	not used – mother board
	03	out 3 – mother board
	02	out 2 – mother board
	01	out 1 – mother board
00	out 0 – mother board	

i_o(8)	<u>bit</u>	<u>description</u>
	15	out 3 board 16in/4out # 1
	14	out 2 board 16in/4out # 1
	13	out 1 board 16in/4out # 1
	12	out 0 board 16in/4out # 1
	11	out 3 board 16in/4out # 2
	10	out 2 board 16in/4out # 2
	09	out 1 board 16in/4out # 2
	08	out 0 board 16in/4out # 2
	07	out 3 board 16in/4out # 3
	06	out 2 board 16in/4out # 3
	05	out 1 board 16in/4out # 3
	04	out 0 board 16in/4out # 3
	03	out 3 board 16in/4out # 4
	02	out 2 board 16in/4out # 4
	01	out 1 board 16in/4out # 4
00	out 0 board 16in/4out # 4	

i_o(9)	<u>bit</u>	<u>description</u>
	15	out 15 board 4in/16out # 1
	14	out 14 board 4in/16out # 1
	13	out 13 board 4in/16out # 1
	12	out 12 board 4in/16out # 1
	11	out 11 board 4in/16out # 1
	10	out 10 board 4in/16out # 1
	09	out 09 board 4in/16out # 1
	08	out 08 board 4in/16out # 1
	07	out 07 board 4in/16out # 1
	06	out 06 board 4in/16out # 1
	05	out 05 board 4in/16out # 1
	04	out 04 board 4in/16out # 1
	03	out 03 board 4in/16out # 1
	02	out 02 board 4in/16out # 1
	01	out 01 board 4in/16out # 1
00	out 00 board 4in/16out # 1	

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<u>i_o(10)</u>	<u>bit</u>	<u>description</u>
	15	out 15 board 4in/16out # 2
	14	out 14 board 4in/16out # 2
	13	out 13 board 4in/16out # 2
	12	out 12 board 4in/16out # 2
	11	out 11 board 4in/16out # 2
	10	out 10 board 4in/16out # 2
	09	out 09 board 4in/16out # 2
	08	out 08 board 4in/16out # 2
	07	out 07 board 4in/16out # 2
	06	out 06 board 4in/16out # 2
	05	out 05 board 4in/16out # 2
	04	out 04 board 4in/16out # 2
	03	out 03 board 4in/16out # 2
	02	out 02 board 4in/16out # 2
	01	out 01 board 4in/16out # 2
	00	out 00 board 4in/16out # 2

<u>i_o(11)</u>	<u>bit</u>	<u>description</u>
	15	out 15 board 4in/16out # 3
	14	out 14 board 4in/16out # 3
	13	out 13 board 4in/16out # 3
	12	out 12 board 4in/16out # 3
	11	out 11 board 4in/16out # 3
	10	out 10 board 4in/16out # 3
	09	out 09 board 4in/16out # 3
	08	out 08 board 4in/16out # 3
	07	out 07 board 4in/16out # 3
	06	out 06 board 4in/16out # 3
	05	out 05 board 4in/16out # 3
	04	out 04 board 4in/16out # 3
	03	out 03 board 4in/16out # 3
	02	out 02 board 4in/16out # 3
	01	out 01 board 4in/16out # 3
	00	out 00 board 4in/16out # 3

<u>i_o(12)</u>	<u>bit</u>	<u>description</u>
	15	out 15 board 4in/16out # 4
	14	out 14 board 4in/16out # 4
	13	out 13 board 4in/16out # 4
	12	out 12 board 4in/16out # 4
	11	out 11 board 4in/16out # 4
	10	out 10 board 4in/16out # 4
	09	out 09 board 4in/16out # 4
	08	out 08 board 4in/16out # 4
	07	out 07 board 4in/16out # 4
	06	out 06 board 4in/16out # 4
	05	out 05 board 4in/16out # 4
	04	out 04 board 4in/16out # 4
	03	out 03 board 4in/16out # 4
	02	out 02 board 4in/16out # 4
	01	out 01 board 4in/16out # 4
	00	out 00 board 4in/16out # 4

g. commands first word

Each bit of the commands register is specified as follows :

<u>Bit</u>	<u>Description</u>	<u>Action</u>
15 (MSB)	Not used	
14	Not used	
13	Not used	
12	Not used	
11	Not used	
10	Not used	
09	Not used	

Calibration commands :

It is possible to start a calibration function from the remote. At the end of the calibration (calibration flag in status registers should be tested to determine when cal functions end), it is possible to verify the calibration error (cal error register) and eventually accept the new zero or span.

<u>Bit</u>	<u>Description</u>	<u>Action</u>
08	Autospan RCAL	Start the autospan function with RCAL method. The Rcal is automatically connected by instrument at the beginning of the function and disconnected at its end. This operation needs a delay of 0.5 seconds. In case a RCAL remote calibration is aborted, the calibration flags will turn off after this delay.
07	Autospan CHAIN	Start the autospan function with CHAINS method.
06	Autospan WTS	Start the autospan function with WTS method. An output of the Microtech can be programmed to automatically load the test weights, this adds a 10 second delay at the beginning and at the end of the calibration function. In case a WTS remote calibration is aborted, the calibration flags will turn off after this time.
05	Autozero	Start the autozero function.
04	Confirm zero/span	At the end of the calibration function, this command tells the instrument to save the new zero or span. If this command is sent during a remote calibration, it aborts the running function.

batch commands :

<u>Bit</u>	<u>Description</u>	<u>Action</u>
03	Stand by Batch	Only if Load Out option is installed. Temporarily stops a Load Out (batch) sequence. Batch can resume if a Start command is sent later.

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02	Stop Batch	Only if Load Out option installed. Stop a Load Out (batch) sequence.
01	Start Batch	Only if Load Out option installed. Start a Load Out (batch) sequence.
00	Reset Alarms	Resets any pending alarm.

In order to give a command, the Host must set the relevant bit to 1 and write (send) the register to the instrument. The action is performed if the write message is accepted.

h. rate

The instantaneous rate in engineering units as currently displayed on the RUN screen

i. load

The instantaneous weight in engineering units.

j. speed

The instantaneous belt speed in engineering units.

k. master_total

The current value of the master totalizer of the integrator.

l. reset_total

The current value of the reset totalizer of the integrator. Reset total can be zeroed by writing zero to this register.

m. operator_total

The current value of the operator totalizer of the integrator. Operator total can be zeroed by writing zero to this register.

NOTE: The register from m. to r. only apply if the optional Load Out option is installed.

n. batch_total

The current contents of the load out totalizer. Usually read at end of batch to check the result of the load out. This register is automatically cleared when a new batch is started.

o. batch_number

The number of the currently running load out or the number of the last finished one. The integrator automatically increments the batch number when a new batch is started.

p. batch_set

The set point for the current or the next load out. Usually entered or downloaded by the user.

q. batch_pre_set

The pre-set point for the current or the next load out. Set by user, defines when the rate is lowered to increase batch accuracy.

r. batch_pre_act

The set point of the preact for the current or next load out. Entered or downloaded by the user (if in MANUAL mode) or calculated by the integrator. Defines when the load out has to stop to compensate the queue of material from the loading point to the scale.

- s. batch_deviation
The maximum acceptable deviation from the batch set point. Usually entered by the user.
- t. scale_capacity
The scale capacity of the scale. Entered by user at first start up, should never be altered.
- u. speed_capacity
The speed capacity of the integrator. Entered or acquired at the first start up, should never be altered.
- v. load_cell_capacity
The load cell capacity of the integrator. Entered at first start up, should never be altered.
- w. high_rate_set
The set point for the alarm of high rate. Entered or downloaded by the user.
- x. low_rate_set
The set point for the alarm of low rate . Entered or downloaded by the user.
- y. high_speed_set
The set point for the alarm og high speed. Entered or downloaded by the user.
- z. low_speed_set
The set point for the alarm of low speed. Entered or downloaded by the user.
- aa. high_load_set
The set point for the alarm of high belt loading. Entered or downloaded by the user.
- bb. low_load_set
The set point for the alarm of high belt loading. Entered or downloaded by the user.
- cc. command second word

Each bit of the commands register is specified as follows:

<u>Bit</u>	<u>Description</u>	<u>Action</u>
15 (MSB)	Not used	
14	Not used	
13	Force output	CUSTOM 7 = OFF
12	Force output	CUSTOM 7 = ON
11	Force output	CUSTOM 6 = OFF
10	Force output	CUSTOM 6 = ON
09	Force output	CUSTOM 5 = OFF
08	Force output	CUSTOM 5 = ON
07	Force output	CUSTOM 4 = OFF
06	Force output	CUSTOM 4 = ON
05	Force output	CUSTOM 3 = OFF
04	Force output	CUSTOM 3 = ON
03	Force output	CUSTOM 2 = OFF
02	Force output	CUSTOM 2 = ON
01	Force output	CUSTOM 1 = OFF
00	Force output	CUSTOM 1 = ON

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dd. reg_set_point_1

Set point of the regulator that can be download by the Master through the serial communication line. This set point will only be used if "SET POINT SOURCE" in CNTRL1 SCROLL 9 is set up for "SERIAL LINE". Otherwise will be ignored.

ee. dsp_set_point

The actual set point of the regulator. May be the same as reg_set_point or a local or analog input depending on the system set up.

ff. ctr_deviation

Current deviation from the set point in per cent.

gg. hi_pos_dev

Set point for the high positive deviation alarm.

hh. hi_hi_pos_dev

Set point for the high high positive deviation alarm.

ii. hi_neg_dev

Set point for the high negative deviation alarm.

ll. hi_hi_neg_dev

Set point for the high high negative deviation alarm.

mm. percent of ingred. $\frac{1}{2}$

It defines the ratio between the actual and remote set-point (optional input in mA).

nn. preset set point

It defines the slow rate factor in percent of actual set-point.

oo. cal_error

Indicates in percent the zero or span error computed at the end of a remote calibration function.

pp. Span

Indicate the span in use in the scale.

qq. Zero

Indicate the zero in use in the scale.

rr. A.Z.T. correction

The AZT function accurately tracks the zero of the scale, by calculating an additional zero constant. The portion of zero due to AZT is not incorporated in the zero constant, but is shown separately.

ss. master_total (only with Modbus protocol)

The current value of the master totalizer of the integrator. (In double format).

tt. reset_total (only with Modbus protocol)

The current value of the reset totalizer of the integrator. (In double format).

uu. operator_total (only with Modbus protocol)

The current value of the operator totalizer of the integrator. (In double format).

vv. Set cont. Value

It is the value of the control output when the option START OUT SET is set to SEL.

aaa. Regulation delay

It is the delay of the regulation at START when the option START OUT SET is set to SEL.

bbb. Out analogic

It is the actual value of the out analogic.

ccc. Proportional band

It is the actual value of the proportional band.

ddd. Integral time

It is the actual value of the integral time.

eee. Deriv. time

It is the actual value of the derivate time.

fff. Damping variable 1

It is the actual value of the process variable damping 1.

ggg. Damping variable 2

It is the actual value of the process variable damping 2.

3.5 PC-Master

The PC-Master protocol is fully described in the following manual (available from Thermo Ramsey on request) :

PC-MASTER COMMUNICATION PROTOCOL

The following messages are used to communicate with MT3000 type of instruments:

- Message #97 : Send a Key to the MT3105
- Message #98 : Send a variables to the MT3105
- Message #99 : Get variables from the MT3105

3.5.1 Description

1. Message #97 : SEND A KEY TO THE 3105

With this command, the code of one or more kays can be sent to the instrument. When the keys are received by the instrument, they are processed as the normal keyboard entries.

QUERY MESSAGE

Begin of frame	STX	02
	DLE	10H
Address	xxx	xxx
Code	97	61H
Stamp	xxx	xxx
Data	KEY	1byte
Error check	xxx	xxx
End of frame	ETX	03

RESPONSE MESSAGE

No response is provided.

TABLE OF THE KEYS			
KEY	HEX CODE	KEY	HEX CODE
UP ARROW	48H	EIGHT	38H
DOWN ARROW	50H	NINE	39H
DECIMAL POINT	2EH	MENU	4DH
CLEAR	53H	RUN	52H
ZERO	30H	F1	3FH
ONE	31H	F2	40H
TWO	32H	F3	41H
THREE	33H	TOTAL	3BH
FOUR	34H	PRINT	3CH
FIVE	35H	START	3DH
SIX	36H	STOP	3EH
SEVEN	37H		

Example 1:

The Host sends the "MENU"key to 3105 (Address of Slave 1) :

<u>HOST (PLC)</u>		<u>SLAVE (3105)</u>
02H	→	
10H		
01H		
61H		
01H		
4DH		
B0H		
03H	→	

2. Message #98 : SEND A VARIABLE TO THE 3105

With this command, the master sends registers to the slave unit.

QUERY MESSAGE

Begin of frame	STX	02
	DLE	10H
Address	xxx	xxx
Code	98	62H
Stamp	xxx	xxx
Data	Address	1WORD
	WordCount	1WORD
	DATA	WordCount WORDS
Error check	xxxxxx	
End of frame	ETX	03

RESPONSE MESSAGE

Begin of frame	STX	02
	DLE	10H
Address	xxx	xxx
Code	98	62H
Stamp	xxx	xxx

Data	Address	1WORD
Error check	WordCount	1WORD
End of frame	xxx	xxx
	ETX	03

Example 1 :

The Host writes the batch setpoint :

Batch set point : 100 Tons

Address of Slave : 1

HOST (PLC) SLAVE

```

02H      →
10H
01H
62H
01H
00H
6CH
00H
02H
42H
C8H
00H
00H
DCH
03H

→
← 02H
   10H
   01H
   62H
   01H
   00H
   6CH
   00H
   02H
   D2H
← 03H
    
```

3. Message #99 : READ REGISTER FROM THE 3105

With this command, the master asks the slave unit for registers.

QUERY MESSAGE

Begin of frame	STX	02
	DLE	10H
Address	xxx	xxx
Code	99	63H
Stamp	xxx	xxx
Data	Address	1WORD
	WordCount	1WORD
Error check	xxx	xxx
End of frame	ETX	03

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RESPONSE MESSAGE

Begin of frame	STX	02
	DLE	10H
Address	xxx	xxx
Code	99	63H
Stamp	xxx	xxx
Data	Address	1WORD
	WordCount	1WORD
	DATA	n. WORDS
Error check	xxx	xxx
End of frame	ETX	03

Example 1 :

The Host reads from the 3105 the batch setpoint :

Batch set point : 200.5 Tons

Address of Slave : 1

HOST (PLC) SLAVE (3105)

```

02H      →
10H
01H
63H
01H
00H
6CH
00H
02H
D3H
03H      →
← 02H
    10H
    01H
    63H
    01H
    00H
    6CH
    00H
    02H
    43H
    48H
    80H
    00H
    DEH
← 03H
    
```

3.5.2 Register Mapping for PC-Master Protocol

register	address	note
success_flag	20 H	0 successful, 1 failed
display(1)	21 H	
display(2)	22 H	
display(3)	23H	
display(4)	24 H	
display(5)	25 H	
display(6)	26 H	
display(7)	27 H	
display(8)	28 H	
display(9)	29 H	
display(10)	2A H	
display(11)	2B H	
display(12)	2C H	
display(13)	2D H	
display(14)	2E H	
display(15)	2F H	
display(16)	30 H	
display(17)	31 H	
display(18)	32 H	
display(19)	33 H	
display(20)	34 H	
display(21)	35 H	
display(22)	36 H	
display(23)	37 H	
display(24)	38 H	
display(25)	39 H	
display(26)	3A H	
display(27)	3B H	
display(28)	3C H	
display(29)	3D H	
display(30)	3E H	
display(31)	3F H	
display(32)	40 H	
display(33)	41 H	
display(34)	42 H	
display(35)	43 H	
display(36)	44 H	
display(37)	45 H	
display(38)	46 H	
display(39)	47 H	
display(40)	48 H	
leds	49 H	
status(1)	4A H	
status(2)	4B H	
alarm_status(1)	4C H	
alarm_status(2)	4D H	
alarm_status(3)	4E H	
i_o(1)	4F H	
i_o(2)	50H	

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register	address	note
i_o(3)	51 H	
i_o(4)	52 H	
i_o(5)	53 H	
i_o(6)	54 H	
i_o(7)	55 H	
i_o(8)	56 H	
i_o(9)	57 H	
i_o(10)	58 H	
i_o(11)	59 H	
i_o(12)	5A H	
commands first word	5B H	
batch_number	5C H	Load out option required
batch_deviation	5D H	Load out option required
percent of ingred. _1	5E H	read only (int. value)
percent of ingred. _2	5F H	read only (int. value)
rate(1)	60 H	
rate(2)	61 H	
load(1)	62 H	
load(2)	63 H	
speed(1)	64 H	
speed(2)	65 H	
master_total(1)	66 H	
master_total(2)	67 H	
reset_total(1)	68 H	
reset_total(2)	69 H	
operator_total(1)	6A H	
operator_total(2)	6B H	
batch_total(1)	6C H	Load out option required
batch_total(2)	6D H	
batch_set_point(1)	6E H	Load out option required
batch_set_point(2)	6F H	
batch_pre_set(1)	70 H	Load out option required
batch_pre_set(2)	71 H	
preset set point (1)	72 H	Load out option required
preset set point (2)	73 H	
batch_pre_act (1)	74 H	Load out option required
batch_pre_act (2)	75 H	
scale_capacity(1)	76 H	
scale_capacity(2)	77 H	
speed_capacity(1)	78 H	
speed_capacity(2)	79 H	
load_cell_capacity(1)	7A H	
load_cell_capacity(2)	7B H	
high_rate_set(1)	7C H	
high_rate_set(2)	7D H	
low_rate_set(1)	7E H	
low_rate_set(2)	7F H	
high_speed_set(1)	80 H	
high_speed_set(2)	81 H	
low_speed_set(1)	82 H	
low_speed_set(2)	83 H	
high_load_set(1)	84 H	

register	address	note
high_load_set(2)	85 H	
low_load_set(1)	86 H	
low_load_set(2)	87 H	
reg_set_point_1 (1)	88 H	
reg_set_point_1 (2)	89 H	
reg_set_point_2 (1)	8A H	
reg_set_point_2 (2)	8B H	
dsp_set_point_1 (1)	8C H	
dsp_set_point_1 (2)	8D H	
dsp_set_point_2 (1)	8E H	
dsp_set_point_2 (2)	8F H	
ctr_deviation_1 (1)	90 H	
ctr_deviation_1 (2)	91 H	
ctr_deviation_2 (1)	92 H	
ctr_deviation_2 (2)	93 H	
hi_pos_dev_1 (1)	94 H	
hi_pos_dev_1 (2)	95 H	
hi_hi_pos_dev_1 (1)	96 H	
hi_hi_pos_dev_1 (2)	97 H	
hi_neg_dev_1 (1)	98 H	
hi_neg_dev_1 (2)	99 H	
hi_hi_neg_dev_1 (1)	9A H	
hi_hi_neg_dev_1 (2)	9B H	
hi_pos_dev_2 (1)	9C H	
hi_pos_dev_2 (2)	9D H	
hi_hi_pos_dev_2 (1)	9E H	
hi_hi_pos_dev_2 (2)	9F H	
hi_neg_dev_2 (1)	A0 H	
hi_neg_dev_2 (2)	A1 H	
hi_hi_neg_dev_2 (1)	A2 H	
hi_hi_neg_dev_2 (2)	A3 H	
cal_error(1)	A4 H	
cal_error(2)	A5 H	
span (1)	A6 H	
span (2)	A7 H	
zero (1)	A8 H	
zero (2)	A9 H	
azt correction (1)	AA H	
azt correction (2)	AB H	
percent of ingred. 1 (1)	AC H	
percent of ingred. 1 (2)	AD H	
percent of ingred. 2 (1)	AE H	
percent of ingred. 2 (2)	AF H	
Master total (1)	B0 H	Only modbus protocol
Master total (2)	B1 H	Only modbus protocol
Master total (3)	B2 H	Only modbus protocol
Master total (4)	B3 H	Only modbus protocol
Reset total (1)	B4 H	Only modbus protocol
Reset total (2)	B5 H	Only modbus protocol
Reset total (3)	B6 H	Only modbus protocol
Reset total (4)	B7 H	Only modbus protocol
Operator total (1)	B8 H	Only modbus protocol


```

DESTINATION DW      (XXH)
BYTE COUNT HI      (00H)
BYTE COUNT LO      (XXH)
no CF               (FFH)
all CPUs            (FFH)
DATA MSB
....
DATA LSB
DLE                 (10H)
ETX                 (03H)
BCC                 (XXH)
→
← DLE (10H)
← STX (02H)
DLE (10H)          →
←
HEADER HI (00H)
HEADER LO (00H)
NOT USED  (00H)
NUMBER ERROR (00H)
DLE (10H)
ETX (03H)
BBC (XXH)

DLE (10H)          →

```

- The Host (PC or PLC) asks for data from the Slave (3105) :

```

HOST (PLC)                SLAVE (3105)
STX                          →
                              ← DLE (10H)
                              →

HEADER HI (00H)
HEADER LO (00H)
COMMAND HI (45H)
COMMAND LO (44H)
DESTINATION DB (00H)
DESTINATION DW (XXH)
BYTE COUNT HI (00H)
BYTE COUNT LO (XXH)
no CF (FFH)
all CPUs (FFH)
DLE (10H)
EXT (03H)
BCC (XXH)
→
← DLE (10H)
← STX (02H)
DLE (10H)          →
←
HEADER HI (00H)
HEADER LO (00H)
NOT USED (00H)
NUMBER ERROR (XXH)
DATA LSB
MAX 127BYTES
DATA MSB
DLE (10H)

```

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DLE (10H) → ETX (03H)
 BBC (XXH)

Example 1 :

The Host wants to write the batch set point :

Set batch : 100.0 Tons

<u>HOST (PLC)</u>		<u>SLAVE (3105)</u>
02H	→	
	←	10H
00H	→	
00H		
41H		
44H		
00H		
6CH		
00H		
02H		
FFH		
FFH		
42H		
C8H		
00H		
00H		
10H		
03H		
F2H	→	
	←	10H
	←	02H
10H	→	
	←	00H
		00H
		00H
		00H
		10H
		03H
		13H
10H	→	

Example 2 :

The Host wants to receive the batch set point :

Batch set point: 100.0 Tons

<u>HOST (PLC)</u>		<u>SLAVE (3105)</u>
02H	→	
	←	10H
00H	→	
00H		
45H		
44H		
00H		

```

6CH
00H
02H
FFH
FFH
10H
03H
7CH          →
              ← 10H
              ← 02H
10H          →
              ← 00H
              00H
              00H
              00H
              42H
              C8H
              00H
              00H
              10H
              03H
              99H
10H          →
    
```

3.6.2 Register Mapping for Siemens 3964R Protocol

register	address	note
success_flag	20 H	0 successful, 1 failed
display(1)	21 H	
display(2)	22 H	
display(3)	23H	
display(4)	24 H	
display(5)	25 H	
display(6)	26 H	
display(7)	27 H	
display(8)	28 H	
display(9)	29 H	
display(10)	2A H	
display(11)	2B H	
display(12)	2C H	
display(13)	2D H	
display(14)	2E H	
display(15)	2F H	
display(16)	30 H	
display(17)	31 H	
display(18)	32 H	
display(19)	33 H	
display(20)	34 H	
display(21)	35 H	
display(22)	36 H	
display(23)	37 H	
display(24)	38 H	
display(25)	39 H	

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register	address	note
display(26)	3A H	
display(27)	3B H	
display(28)	3C H	
display(29)	3D H	
display(30)	3E H	
display(31)	3F H	
display(32)	40 H	
display(33)	41 H	
display(34)	42 H	
display(35)	43 H	
display(36)	44 H	
display(37)	45 H	
display(38)	46 H	
display(39)	47 H	
display(40)	48 H	
leds	49 H	
status(1)	4A H	
status(2)	4B H	
alarm_status(1)	4C H	
alarm_status(2)	4D H	
alarm_status(3)	4E H	
i_o(1)	4F H	
i_o(2)	50H	
i_o(3)	51 H	
i_o(4)	52 H	
i_o(5)	53 H	
i_o(6)	54 H	
i_o(7)	55 H	
i_o(8)	56 H	
i_o(9)	57 H	
i_o(10)	58 H	
i_o(11)	59 H	
i_o(12)	5A H	
commands first word	5B H	
batch_number	5C H	Load out option required
batch_deviation	5D H	Load out option required
percent of ingred. _1	5E H	read only (int. value)
percent of ingred. _2	5F H	read only (int. value)
rate(1)	60 H	
rate(2)	61 H	
load(1)	62 H	
load(2)	63 H	
speed(1)	64 H	
speed(2)	65 H	
master_total(1)	66 H	
master_total(2)	67 H	
reset_total(1)	68 H	
reset_total(2)	69 H	
operator_total(1)	6A H	
operator_total(2)	6B H	
batch_total(1)	6C H	Load out option required
batch_total(2)	6D H	

register	address	note
batch_set_point(1)	6E H	Load out option required
batch_set_point(2)	6F H	
batch_pre_set(1)	70 H	Load out option required
batch_pre_set(2)	71 H	
preset set point (1)	72 H	Load out option required
preset set point (2)	73 H	
batch_pre_act (1)	74 H	Load out option required
batch_pre_act (2)	75 H	
scale_capacity(1)	76 H	
scale_capacity(2)	77 H	
speed_capacity(1)	78 H	
speed_capacity(2)	79 H	
load_cell_capacity(1)	7A H	
load_cell_capacity(2)	7B H	
high_rate_set(1)	7C H	
high_rate_set(2)	7D H	
low_rate_set(1)	7E H	
low_rate_set(2)	7F H	
high_speed_set(1)	80 H	
high_speed_set(2)	81 H	
low_speed_set(1)	82 H	
low_speed_set(2)	83 H	
high load set(1)	84 H	
high load set(2)	85 H	
low load set(1)	86 H	
low load set(2)	87 H	
reg_set_point_1 (1)	88 H	
reg_set_point_1 (2)	89 H	
reg_set_point_2 (1)	8A H	
reg_set_point_2 (2)	8B H	
dsp_set_point_1 (1)	8C H	
dsp_set_point_1 (2)	8D H	
dsp_set_point_2 (1)	8E H	
dsp_set_point_2 (2)	8F H	
ctr_deviation_1 (1)	90 H	
ctr_deviation_1 (2)	91 H	
ctr_deviation_2 (1)	92 H	
ctr_deviation_2 (2)	93 H	
hi_pos_dev_1 (1)	94 H	
hi_pos_dev_1 (2)	95 H	
hi hi_pos_dev_1 (1)	96 H	
hi hi_pos_dev_1 (2)	97 H	
hi_neg_dev_1 (1)	98 H	
hi_neg_dev_1 (2)	99 H	
hi hi_neg_dev_1 (1)	9A H	
hi hi_neg_dev_1 (2)	9B H	
hi_pos_dev_2 (1)	9C H	
hi_pos_dev_2 (2)	9D H	
hi hi_pos_dev_2 (1)	9E H	
hi hi_pos_dev_2 (2)	9F H	
hi_neg_dev_2 (1)	A0 H	
hi_neg_dev_2 (2)	A1 H	

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register	address	note
hi hi neg dev 2 (1)	A2 H	
hi hi neg dev 2 (2)	A3 H	
cal_error(1)	A4 H	
cal_error(2)	A5 H	
span (1)	A6 H	
span (2)	A7 H	
zero (1)	A8 H	
zero (2)	A9 H	
azt correction (1)	AA H	
azt correction (2)	AB H	
percent of ingred. 1 (1)	AC H	
percent of ingred. 1 (2)	AD H	
percent of ingred. 2 (1)	AE H	
percent of ingred. 2 (2)	AF H	
Master total (1)	B0 H	Only modbus protocol
Master total (2)	B1 H	Only modbus protocol
Master total (3)	B2 H	Only modbus protocol
Master total (4)	B3 H	Only modbus protocol
Reset total (1)	B4 H	Only modbus protocol
Reset total (2)	B5 H	Only modbus protocol
Reset total (3)	B6 H	Only modbus protocol
Reset total (4)	B7 H	Only modbus protocol
Operator total (1)	B8 H	Only modbus protocol
Operator total (2)	B9 H	Only modbus protocol
Operator total (3)	BA H	Only modbus protocol
Operator total (4)	BB H	Only modbus protocol
Out Analogic 1 (1)	BC H	
Out Analogic 1 (2)	BD H	
Out Analogic 2 (1)	BE H	
Out Analogic 2 (2)	BF H	
Out Analogic 3 (1)	C0 H	
Out Analogic 3 (2)	C1 H	
Out Analogic 4 (1)	C2 H	
Out Analogic 4 (2)	C3 H	
Integral Time (1) loop 1	C4 H	
Integral Time (2) loop 1	C5 H	
Integral Time (1) loop 2	C6 H	
Integral Time (2) loop 2	C7 H	
Deriv. Time (1) loop 1	C8 H	
Deriv. Time (2) loop 1	C9 H	
Deriv. Time (1) loop 2	CA H	
Deriv. Time (2) loop 2	CB H	
Set cont. value loop 1	CC H	
Set cont. value loop 2	CD H	
Regulat. delay loop 1	CE H	
Regulat. delay loop 2	CF H	
Prop. band loop 1	D0 H	
Prop. band loop 2	D1 H	
Var. 1 damping	D2 H	
Var. 2 damping	D3 H	
commands second word	D4 H	

3.7 Modbus

3.7.1 Description

This protocol has been implemented as described in : - "Gould Modicon Modbus Protocol" – Reference Guide – November 1993 – Rev.A (Gould Inc. Programmable Control Division).

NOTE: Only a subset of the protocol has been implemented, as described in this chapter.

- Message of data query from host (PC or PLC) to Slave (3105) (code 03H)

QUERY

Address	xxx
function	03H
add.hi	xxx
add.lo	xxx
n.data hi	xxx
n.data lo	xxx
crc16 lo	xxx
crc16 hi	xxx

REPOSE MESSAGE

Address	xxx
function	03H
byte cnt	xxx
data MSB	xxx
...	xxx
data LSB	xxx
crc16 lo	xxx
crc16 hi	xxx

Example 1 :

The Host wants to receive the batch set point :

Set point : 100.0 Tons

Address of Slave: 01

<u>HOST (PLC)</u>		<u>SLAVE (3105)</u>
01H	→	
03H		
00H		
06C		
00H		
02H		
04H		
16H	→	
	←	01H
		03H
		04H

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```

                                00H
                                00H
                                42H
                                C8H
                                CBH
←                               05H

```

- Message of data sending from host (PC or PLC) to Slave (3105) (code 10H)

QUERY

```

Address          xxx
function         10H
add.hi           xxx
add.lo           xxx
n.data hi       xxx
n.data lo       xxx
n. bytes        xxx
data MSB        xxx
...             xxx
data LSB        xxx
crc16 lo        xxx
crc16 hi        xxx

```

REPONSE MESSAGE

```

Address          xxx
function         10H
add. hi         xxx
add. lo         xxx
n. data hi      xxx
n. data lo      xxx
crc16 lo        xxx
crc16 hi        xxx

```

Example 1 :

The Host wants to write the batch set point :

Batch Set point : 100.0 Tons

Address of Slave: 1

HOST (PLC) SLAVE (3105)

```

01H                      →
10H
00H
6CH
00H
02H
04H
00H
00H
42H
C8H

```


5CH
00H
00H
49H
D8H
←

3.7.2 Register Mapping for Modbus

register	address	note
success_flag	33	0 successful, 1 failed
display(1)	34	
display(2)	35	
display(3)	36	
display(4)	37	
display(5)	38	
display(6)	39	
display(7)	40	
display(8)	41	
display(9)	42	
display(10)	43	
display(11)	44	
display(12)	45	
display(13)	46	
display(14)	47	
display(15)	48	
display(16)	49	
display(17)	50	
display(18)	51	
display(19)	52	
display(20)	53	
display(21)	54	
display(22)	55	
display(23)	56	
display(24)	57	
display(25)	58	
display(26)	59	
display(27)	60	
display(28)	61	
display(29)	62	
display(30)	63	
display(31)	64	
display(32)	65	
display(33)	66	
display(34)	67	
display(35)	68	
display(36)	69	
display(37)	70	
display(38)	71	
display(39)	72	
display(40)	73	
leds	74	
status(1)	75	
status(2)	76	

register	address	note
alarm_status(1)	77	
alarm_status(2)	78	
alarm_status(3)	79	
i_o(1)	80	
i_o(2)	81	
i_o(3)	82	
i_o(4)	83	
i_o(5)	84	
i_o(6)	85	
i_o(7)	86	
i_o(8)	87	
i_o(9)	88	
i_o(10)	89	
i_o(11)	90	
i_o(12)	91	
commands first word	92	
batch_number	93	Load out option required
batch_deviation	94	Load out option required
percent of ingred. _1	95	read only (int. value)
percent of ingred. _2	96	read only (int. value)
rate(1)	97	
rate(2)	98	
load(1)	99	
load(2)	100	
speed(1)	101	
speed(2)	102	
master_total(1)	103	
master_total(2)	104	
reset_total(1)	105	
reset_total(2)	106	
operator_total(1)	107	
operator_total(2)	108	
batch_total(1)	109	Load out option required
batch_total(2)	110	
batch_set_point(1)	111	Load out option required
batch_set_point(2)	112	
batch_pre_set(1)	113	Load out option required
batch_pre_set(2)	114	
preset set point (1)	115	Load out option required
preset set point (2)	116	
batch_pre_act (1)	117	Load out option required
batch_pre_act (2)	118	
scale_capacity(1)	119	
scale_capacity(2)	120	
speed_capacity(1)	121	
speed_capacity(2)	122	
load_cell_capacity(1)	123	
load_cell_capacity(2)	124	
high_rate_set(1)	125	
high_rate_set(2)	126	
low_rate_set(1)	127	
low_rate_set(2)	128	

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register	address	note
high_speed_set(1)	129	
high_speed_set(2)	130	
low_speed_set(1)	131	
low_speed_set(2)	132	
high_load_set(1)	133	
high_load_set(2)	134	
low_load_set(1)	135	
low_load_set(2)	136	
reg_set_point_1 (1)	137	
reg_set_point_1 (2)	138	
reg_set_point_2 (1)	139	
reg_set_point_2 (2)	140	
dsp_set_point_1 (1)	141	
dsp_set_point_1 (2)	142	
dsp_set_point_2 (1)	143	
dsp_set_point_2 (2)	144	
ctr_deviation_1 (1)	145	
ctr_deviation_1 (2)	146	
ctr_deviation_2 (1)	147	
ctr_deviation_2 (2)	148	
hi_pos_dev_1 (1)	149	
hi_pos_dev_1 (2)	150	
hi hi_pos_dev_1 (1)	151	
hi hi_pos_dev_1 (2)	152	
hi_neg_dev_1 (1)	153	
hi_neg_dev_1 (2)	154	
hi hi_neg_dev_1 (1)	155	
hi hi_neg_dev_1 (2)	156	
hi_pos_dev_2 (1)	157	
hi_pos_dev_2 (2)	158	
hi hi_pos_dev_2 (1)	159	
hi hi_pos_dev_2 (2)	160	
hi_neg_dev_2 (1)	161	
hi_neg_dev_2 (2)	162	
hi hi_neg_dev_2 (1)	163	
hi hi_neg_dev_2 (2)	164	
cal_error(1)	165	
cal_error(2)	166	
span (1)	167	
span (2)	168	
zero (1)	169	
zero (2)	170	
azt correction (1)	171	
azt correction (2)	172	
percent of ingred. _1 (1)	173	
percent of ingred. _1 (2)	174	
percent of ingred. _2 (1)	175	
percent of ingred. _2 (2)	176	
Master total (1)	177	Only modbus protocol
Master total (2)	178	Only modbus protocol
Master total (3)	179	Only modbus protocol
Master total (4)	180	Only modbus protocol

Reset total (1)	181	Only modbus protocol
Reset total (2)	182	Only modbus protocol
Reset total (3)	183	Only modbus protocol
Reset total (4)	184	Only modbus protocol
Operator total (1)	185	Only modbus protocol
Operator total (2)	186	Only modbus protocol
Operator total (3)	187	Only modbus protocol
Operator total (4)	188	Only modbus protocol
Out Analogic 1 (1)	189	
Out Analogic 1 (2)	190	
Out Analogic 2 (1)	191	
Out Analogic 2 (2)	192	
Out Analogic 3 (1)	193	
Out Analogic 3 (2)	194	
Out Analogic 4 (1)	195	
Out Analogic 4 (2)	196	
Integral Time (1) loop 1	197	
Integral Time (2) loop 1	198	
Integral Time (1) loop 2	199	
Integral Time (2) loop 2	200	
Deriv. Time (1) loop 1	201	
Deriv. Time (2) loop 1	202	
Deriv. Time (1) loop 2	203	
Deriv. Time (2) loop 2	204	
Set cont. value loop 1	205	
Set cont. value loop 2	206	
Regulat. delay loop 1	207	
Regulat. delay loop 2	208	
Prop. band loop 1	209	
Prop. band loop 2	210	
Var. 1 damping	211	
Var. 2 damping	212	
commands second word	213	

3.8 Allen-Bradley DF1 (PLC-5)

3.8.1 Description

The DF1 is a proprietary protocol of Allen-Bradley. The protocol has been implemented according to : Allen-Bradley "Reference Manual–Data Highway / Data Highway Plus Protocol and Command Set".Pubblicat. 1770-6.5,16 September 1991.

WARNING

ONLY A SUBSET OF THE PROTOCOL HAS BEEN IMPLEMENTED. THE COMMANDS USED TO READ OR WRITE THE REGISTERS ARE : TYPED READ (CODE 68H) AND TYPED WRITE (67H).

- Connect message

This message must be sent from Host to Slave before a request of sending data can be performed.

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<u>HOST (PLC)</u>		<u>SLAVE (3105)</u>
DLE	(10H)	→
SOH	(01H)	
ADDRESS OF SLAVE		
DLE	(10H)	
STX	(02H)	
ADDRESS OF SLAVE		
ADDRESS OF HOST		
COMMAND	(0F H)	
STS	(00H)	
TMS	(xxH)	
TMS	(xxH)	
FNC	(68 H)	
PACKET OFFSET (LOW)		
PACKET OFFSET (HIGHT)		
TOTAL TRANS (LOW)		
TOTAL TRANS (HIGH)		
ADDRESS OF DATA (FIRST BYTE)		
ADDRESS OF DATA (SECOND BYTE)		
ADDRESS OF DATA (THIRD BYTE)		
ADDRESS OF DATA (FOURTH BYTE)		
SIZE OF DATA IN ELEMENTS (LOW)		
SIZE OF DATA IN ELEMENTS (HIGH)		
DLE	(10H)	
ETX	(03H)	
BCC		→
		← DLE (10H)
		← ACK (06H)

- The HOST (PLC) asks for data from the Slave (3105) :
 This message is sent from the Host to the Slave to request a certain number of data:

<u>HOST (PLC)</u>		<u>SLAVE (3105)</u>
DLE	(10H)	→
ENQ	(05H)	
ADDRESS SLAVE		
BCC		→
		←
		DLE (10H)
		STX (02H)
		ADDRESS HOST
		ADDRESS SLAVE
		4FH (COMMAND)
		STS (00H)
		TMS (xxH)
		TMS (xxH)
		TYME DATA PARAMETER
		DATA LSB MSB
	
		DATA LSB MSB
		DLE (10H)
		ETX (03H)

```

                ←   BCC
DLE           (10H) →
ACK           (06H) →
    
```

- The HOST (PLC) sends data to the Slave (3105) :
This message is used from the Host to the Slave to download registers into the Slave unit.

```

HOST (PLC)           SLAVE (3105)
DLE           (10H)   →
SOH           (01H)
ADDRESS SLAVE
DLE           (10H)
STX           (02H)
ADDRESS SLAVE
ADDRESS HOST
COMMAND (0FH)
STS           (00H)
TMS           (xxH)
TMS           (xxH)
FNC           (67 H)
PACKET OFFSET (LOW)
PACKET OFFSET (HIGH)
TOTAL TRANS (LOW)
TOTAL TRANS (HIGH)
ADDRESS OF DATA (FIRST BYTE)
ADDRESS OF DATA (SECOND BYTE)
ADDRESS OF DATA (THIRD BYTE)
ADDRESS OF DATA (FOURTH BYTE)
TYPE DATA PARAMETER
    
```

DATA LSB MSB

.....

DATA LSB MSB

```

DLE           (10H)
ETX           (03H)
BCC
    
```

```

                →
                ←   DLE           (10H)
                ←   ACK           (06H)
    
```

- The HOST (PLC) asks the Slave (3105) if data were received o.k. :

```

HOST (PLC)           SLAVE (3105)
DLE           (10H)   →
ENQ           (05H)
ADDRESS OF SLAVE
BCC
                →
                ←   DLE   (10H)
                ←   STX   (02H)
                ADDRESS OF HOST
                ADDRESS OF SLAVE
    
```


05H		
01H		
FFH	→	
	←	10H
		02H
		02H
		01H
		4FH
		00H
		00H
		00H
		99H
		09H
		06H
		94H
		08H
		00H
		80H
		48H
		43H
		10H
		03H
	←	5FH
10H	→	
06H	→	

Example 2 :

The Host sends to slave the batch set point :

Batch Set point : 200.5 Tons

Address of Slave: 01

Address of Host: 02+

<u>HOST (PLC)</u>		<u>SLAVE (3105)</u>
-------------------	--	---------------------

10H	→
01H	
01H	
10H	
02H	
01H	
02H	
0FH	
00H	
00H	
00H	
67H	
00H	
00H	
01H	
00H	
07H	
00H	
08H	

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07H
99H
09H
06H
94H
08H

00H
80H
48H
43H
10H
03H
20H

→
← 10H
← 06H
→

10H
05H
01H
FFH

→
← 10H
02H
02H
01H
4FH
00H
00H
00H
10H
03H
AEH

10H
06H
→
→

3.8.2 Register Mapping for DF1 Allen-Bradley (PLC-5)

register	address	note
success_flag	N7 : 0	0 successful, 1 failed
display(1)	N7 : 1	
display(2)	N7 : 2	
display(3)	N7 : 3	
display(4)	N7 : 4	
display(5)	N7 : 5	
display(6)	N7 : 6	
display(7)	N7 : 7	
display(8)	N7 : 8	
display(9)	N7 : 9	
display(10)	N7 : 10	
display(11)	N7 : 11	
display(12)	N7 : 12	
display(13)	N7 : 13	
display(14)	N7 : 14	
display(15)	N7 : 15	
display(16)	N7 : 16	
display(17)	N7 : 17	
display(18)	N7 : 18	
display(19)	N7 : 19	
display(20)	N7 : 20	
display(21)	N7 : 21	
display(22)	N7 : 22	
display(23)	N7 : 23	
display(24)	N7 : 24	
display(25)	N7 : 25	
display(26)	N7 : 26	
display(27)	N7 : 27	
display(28)	N7 : 28	
display(29)	N7 : 29	
display(30)	N7 : 30	
display(31)	N7 : 31	
display(32)	N7 : 32	
display(33)	N7 : 33	
display(34)	N7 : 34	
display(35)	N7 : 35	
display(36)	N7 : 36	
display(37)	N7 : 37	
display(38)	N7 : 38	
display(39)	N7 : 39	
display(40)	N7 : 40	
leds	N7 : 41	
status(1)	N7 : 42	
status(2)	N7 : 43	
alarm_status(1)	N7 : 44	
alarm_status(2)	N7 : 45	
alarm_status(3)	N7 : 46	
i_o(1)	N7 : 47	
i_o(2)	N7 : 48	
i_o(3)	N7 : 49	

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register	address	note
i_o(4)	N7 : 50	
i_o(5)	N7 : 51	
i_o(6)	N7 : 52	
i_o(7)	N7 : 53	
i_o(8)	N7 : 54	
i_o(9)	N7 : 55	
i_o(10)	N7 : 56	
i_o(11)	N7 : 57	
i_o(12)	N7 : 58	
commands first word	N7 : 59	
batch_number	N7 : 60	Load out option required
batch_deviation	N7 : 61	Load out option required
percent of ingred. 1	N7 : 62	read only (int. value)
percent of ingred. 2	N7 : 63	read only (int. value)
rate(1)	F8 : 0	
rate(2)		
load(1)	F8 : 1	
load(2)		
speed(1)	F8 : 2	
speed(2)		
master_total(1)	F8 : 3	
master_total(2)		
reset_total(1)	F8 : 4	
reset_total(2)		
operator_total(1)	F8 : 5	
operator_total(2)		
batch_total(1)	F8 : 6	Load out option required
batch_total(2)		
batch_set_point(1)	F8 : 7	Load out option required
batch_set_point(2)		
batch_pre_set(1)	F8 : 8	Load out option required
batch_pre_set(2)		
preset set point (1)	F8 : 9	Load out option required
preset set point (2)		
batch_pre_act (1)	F8 : 10	Load out option required
batch_pre_act (2)		
scale_capacity(1)	F8 : 11	
scale_capacity(2)		
speed_capacity(1)	F8 : 12	
speed_capacity(2)		
load_cell_capacity(1)	F8 : 13	
load_cell_capacity(2)		
high_rate_set(1)	F8 : 14	
high_rate_set(2)		
low_rate_set(1)	F8 : 15	
low_rate_set(2)		
high_speed_set(1)	F8 : 16	
high_speed_set(2)		
low_speed_set(1)	F8 : 17	
low_speed_set(2)		
high_load_set(1)	F8 : 18	
high_load_set(2)		

register	address	note
low load set(1)	F8 : 19	
low load set(2)		
reg_set_point_1 (1)	F8 : 20	
reg_set_point_1 (2)		
reg_set_point_2 (1)	F8 : 21	
reg_set_point_2 (2)		
dsp_set_point_1 (1)	F8 : 22	
dsp_set_point_1 (2)		
dsp_set_point_2 (1)	F8 : 23	
dsp_set_point_2 (2)		
ctr_deviation_1 (1)	F8 : 24	
ctr_deviation_1 (2)		
ctr_deviation_2 (1)	F8 : 25	
ctr_deviation_2 (2)		
hi_pos_dev_1 (1)	F8 : 26	
hi_pos_dev_1 (2)		
hi_hi_pos_dev_1 (1)	F8 : 27	
hi_hi_pos_dev_1 (2)		
hi_neg_dev_1 (1)	F8 : 28	
hi_neg_dev_1 (2)		
hi_hi_neg_dev_1 (1)	F8 : 29	
hi_hi_neg_dev_1 (2)		
hi_pos_dev_2 (1)	F8 : 30	
hi_pos_dev_2 (2)		
hi_hi_pos_dev_2 (1)	F8 : 31	
hi_hi_pos_dev_2 (2)		
hi_neg_dev_2 (1)	F8 : 32	
hi_neg_dev_2 (2)		
hi_hi_neg_dev_2 (1)	F8 : 33	
hi_hi_neg_dev_2 (2)		
cal_error(1)	F8 : 34	
cal_error(2)		
span (1)	F8 : 35	
span (2)		
zero (1)	F8 : 36	
zero (2)		
azt correction (1)	F8 : 37	
azt correction (2)		
percent of ingred. 1 (1)	F8 : 38	
percent of ingred. 1 (2)		
percent of ingred. 2 (1)	F8 : 39	
percent of ingred. 2 (2)		
Master total (1)		Only modbus protocol
Master total (2)		Only modbus protocol
Master total (3)		Only modbus protocol
Master total (4)		Only modbus protocol
Reset total (1)		Only modbus protocol
Reset total (2)		Only modbus protocol
Reset total (3)		Only modbus protocol
Reset total (4)		Only modbus protocol
Operator total (1)		Only modbus protocol
Operator total (2)		Only modbus protocol

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register	address	note
Operator total (3)		Only modbus protocol
Operator total (4)		Only modbus protocol
Out Analogic 1 (1)	F8 : 46	
Out Analogic 1 (2)		
Out Analogic 2 (1)	F8 : 47	
Out Analogic 2 (2)		
Out Analogic 3 (1)	F8 : 48	
Out Analogic 3 (2)		
Out Analogic 4 (1)	F8 : 49	
Out Analogic 4 (2)		
Integral Time (1) loop 1	F8 : 50	
Integral Time (2) loop 1		
Integral Time (1) loop 2	F8 : 51	
Integral Time (2) loop 2		
Deriv. Time (1) loop 1	F8 : 52	
Deriv. Time (2) loop 1		
Deriv. Time (1) loop 2	F8 : 53	
Deriv. Time (2) loop 2		
Set cont. value loop 1	N7 : 172	
Set cont. value loop 2	N7 : 173	
Regulat. delay loop 1	N7 : 174	
Regulat. delay loop 2	N7 : 175	
Prop. band loop 1	N7 : 176	
Prop. band loop 2	N7 : 177	
Var. 1 damping	N7 : 178	
Var. 2 damping	N7 : 179	
commands second word	N7 : 180	

Chapter 4 Maintenance

4.1 General

Refer to the Micro-Tech 3105 Belt Feeder Controller manual for maintenance information.

Chapter 5 Parts

5.1 General

Refer to the Micro-Tech 3105 Belt Feeder Controller manual for parts information.